



Deterministic submanifolds and analytic solution of the stochastic differential equation describing a continuously measured qubit

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Measuring fluorescence of a qubit (slides of Benjamin Huard)

A positivity preserving numerical scheme for quantum filtering

The deterministic surface and integral quantities

When is a qubit confined to a deterministic surface ?

Conclusion

A positivity preserving numerical scheme: diffusive case ¹

With a single imperfect measure $d\mathbf{y}_t = \sqrt{\eta} \text{Tr} \left((\mathbf{L} + \mathbf{L}^\dagger) \rho_t \right) dt + d\mathbf{W}_t$ and detection efficiency $\eta \in [0, 1]$, the quantum state ρ_t is usually mixed and obeys to

$$d\rho_t = \left(-\frac{i}{\hbar} [\mathbf{H}, \rho_t] + \mathbf{L}\rho_t\mathbf{L}^\dagger - \frac{1}{2} \left(\mathbf{L}^\dagger\mathbf{L}\rho_t + \rho_t\mathbf{L}^\dagger\mathbf{L} \right) \right) dt + \sqrt{\eta} \left(\mathbf{L}\rho_t + \rho_t\mathbf{L}^\dagger - \text{Tr} \left((\mathbf{L} + \mathbf{L}^\dagger) \rho_t \right) \rho_t \right) d\mathbf{W}_t$$

driven by the Wiener process $d\mathbf{W}_t$ (Gaussian law of mean 0 and variance dt).

With **Itô rules**, it can be written as the following "discrete-time" Markov model

$$\rho_{t+dt} = \frac{\mathbf{M}_{d\mathbf{y}_t} \rho_t \mathbf{M}_{d\mathbf{y}_t}^\dagger + (1 - \eta) \mathbf{L} \rho_t \mathbf{L}^\dagger dt}{\text{Tr} \left(\mathbf{M}_{d\mathbf{y}_t} \rho_t \mathbf{M}_{d\mathbf{y}_t}^\dagger + (1 - \eta) \mathbf{L} \rho_t \mathbf{L}^\dagger dt \right)}$$

with $\mathbf{M}_{d\mathbf{y}_t} = \mathbf{I} + \left(-\frac{i}{\hbar} \mathbf{H} - \frac{1}{2} \left(\mathbf{L}^\dagger \mathbf{L} \right) \right) dt + \sqrt{\eta} d\mathbf{y}_t \mathbf{L}$. The probability to detect $d\mathbf{y}_t$ is given by the following density

$$\mathbb{P} \left(d\mathbf{y}_t \in [s, s + ds] \right) = \frac{\text{Tr} \left(\mathbf{M}_s \rho_t \mathbf{M}_s^\dagger + (1 - \eta) \mathbf{L} \rho_t \mathbf{L}^\dagger dt \right)}{\sqrt{2\pi}} e^{-\frac{s^2}{2dt}} ds$$

close to a Gaussian law of variance dt and mean $\sqrt{\eta} \text{Tr} \left((\mathbf{L} + \mathbf{L}^\dagger) \rho_t \right) dt$.

¹H. Amini, M. Mirrahimi, P.R. IEEE CDC, 2011. P.R., J. Ralph PRA 2015.

The quantum state ρ_t is usually mixed and obeys to

$$d\rho_t = \left(-i[H, \rho_t] + \sum_{\nu} L_{\nu} \rho_t L_{\nu}^{\dagger} - \frac{1}{2}(L_{\nu}^{\dagger} L_{\nu} \rho_t + \rho_t L_{\nu}^{\dagger} L_{\nu}) + V_{\mu} \rho_t V_{\mu}^{\dagger} - \frac{1}{2}(V_{\mu}^{\dagger} V_{\mu} \rho_t + \rho_t V_{\mu}^{\dagger} V_{\mu}) \right) dt \\ + \sum_{\nu} \sqrt{\eta_{\nu}} \left(L_{\nu} \rho_t + \rho_t L_{\nu}^{\dagger} - \text{Tr} \left((L_{\nu} + L_{\nu}^{\dagger}) \rho_t \right) \rho_t \right) dW_{\nu,t} \\ + \sum_{\mu} \left(\frac{\bar{\theta}_{\mu} \rho_t + \sum_{\mu'} \bar{\eta}_{\mu, \mu'} V_{\mu'} \rho_t V_{\mu'}^{\dagger}}{\bar{\theta}_{\mu} + \sum_{\mu'} \bar{\eta}_{\mu, \mu'} \text{Tr} \left(V_{\mu'} \rho_t V_{\mu'}^{\dagger} \right)} - \rho_t \right) \left(dN_{\mu}(t) - \left(\bar{\theta}_{\mu} + \sum_{\mu'} \bar{\eta}_{\mu, \mu'} \text{Tr} \left(V_{\mu'} \rho_t V_{\mu'}^{\dagger} \right) \right) dt \right)$$

where $\eta_{\nu} \in [0, 1]$, $\bar{\theta}_{\mu}, \bar{\eta}_{\mu, \mu'} \geq 0$ with $\bar{\eta}_{\mu'} = \sum_{\mu} \bar{\eta}_{\mu, \mu'} \leq 1$ are parameters modelling measurements imperfections.

If, for some μ , $N_{\mu}(t + dt) - N_{\mu}(t) = 1$, we have $\rho_{t+dt} = \frac{\bar{\theta}_{\mu} \rho_t + \sum_{\mu'} \bar{\eta}_{\mu, \mu'} V_{\mu'} \rho_t V_{\mu'}^{\dagger}}{\bar{\theta}_{\mu} + \sum_{\mu'} \bar{\eta}_{\mu, \mu'} \text{Tr} \left(V_{\mu'} \rho_t V_{\mu'}^{\dagger} \right)}$.

When $\forall \mu$, $dN_{\mu}(t) = 0$, we have

$$\rho_{t+dt} = \frac{M_{dy_t} \rho_t M_{dy_t}^{\dagger} + \sum_{\nu} (1 - \eta_{\nu}) L_{\nu} \rho_t L_{\nu}^{\dagger} dt + \sum_{\mu} (1 - \bar{\eta}_{\mu}) V_{\mu} \rho_t V_{\mu}^{\dagger} dt}{\text{Tr} \left(M_{dy_t} \rho_t M_{dy_t}^{\dagger} + \sum_{\nu} (1 - \eta_{\nu}) L_{\nu} \rho_t L_{\nu}^{\dagger} dt + \sum_{\mu} (1 - \bar{\eta}_{\mu}) V_{\mu} \rho_t V_{\mu}^{\dagger} dt \right)}$$

with $M_{dy_t} = I + \left(-iH - \frac{1}{2} \sum_{\nu} L_{\nu}^{\dagger} L_{\nu} + \frac{1}{2} \sum_{\mu} \left(\bar{\eta}_{\mu} \text{Tr} \left(V_{\mu} \rho_t V_{\mu}^{\dagger} \right) I - V_{\mu}^{\dagger} V_{\mu} \right) \right) dt + \sum_{\nu} \sqrt{\eta_{\nu}} dy_{\nu,t} L_{\nu}$ and where $dy_{\nu,t} = \sqrt{\eta_{\nu}} \text{Tr} \left((L_{\nu} + L_{\nu}^{\dagger}) \rho_t \right) dt + dW_{\nu,t}$.

²H. Amini, C. Pellegrini, P.R.: Russian Journal of Mathematical Physics, 2014.

P.R.: Proceedings of International Congress of Mathematicians, Seoul 2014 (arXiv:1407.7810).

The SME ($\gamma_1 = 1$ here)

$$d\rho_t = \left(\sigma_- \rho \sigma_+ - \frac{\sigma_+ \sigma_- \rho + \rho \sigma_+ \sigma_-}{2} \right) dt \\ + \sqrt{\frac{\eta}{2}} (\sigma_- \rho + \rho \sigma_+ - \text{Tr}(\sigma_x \rho) \rho) dW_I + \sqrt{\frac{\eta}{2}} (i\sigma_- \rho - i\rho \sigma_+ - \text{Tr}(\sigma_y \rho) \rho) dW_Q$$

reads with the Bloch coordinates (x, y, z)

$$dx_t = -\frac{1}{2} x_t dt + \sqrt{\frac{\eta}{2}} \left((1 + z_t - x_t^2) dW_I - x_t y_t dW_Q \right) \\ dy_t = -\frac{1}{2} y_t dt + \sqrt{\frac{\eta}{2}} \left(-x_t y_t dW_I + (1 + z_t - y_t^2) dW_Q \right) \\ dz_t = -(1 + z_t) dt - \sqrt{\frac{\eta}{2}} (1 + z_t) (x_t dW_I + y_t dW_Q)$$

For any realization of starting from the same initial point (x_0, y_0, z_0) we have

$$\frac{1}{2} (x_t^2 + y_t^2) + c_t (1 + z_t)^2 - (1 + z_t) = 0$$

where $c_t = (c_0 - \frac{\eta}{2}) e^t + \frac{\eta}{2}$ remains in $[\frac{1}{2}, +\infty)$ and $c_0 = \frac{x_0^2 + y_0^2}{2(1+z_0)^2} + \frac{1}{1+z_0}$.

³Ph. Campagne-Ibarcq et al. PRX 2016.

The solution of

$$dx_t = -\frac{1}{2}x_t dt + \sqrt{\frac{\eta}{2}} \left((1 + z_t - x_t^2) dW_I - x_t y_t dW_Q \right)$$

$$dy_t = -\frac{1}{2}y_t dt + \sqrt{\frac{\eta}{2}} \left(-x_t y_t dW_I + (1 + z_t - y_t^2) dW_Q \right)$$

$$dz_t = -(1 + z_t) dt - \sqrt{\frac{\eta}{2}} (1 + z_t) (x_t dW_I + y_t dW_Q)$$

can be computed from simple integrals of the signals $dl_t = \sqrt{\frac{\eta}{2}} x_t dt + dW_I$ and

$dQ_t = \sqrt{\frac{\eta}{2}} y_t dt + dW_Q$. This results from

$$d\left(\frac{x}{1+z}\right) = \frac{1}{2} \left(\frac{x_t}{1+z_t}\right) dt + \sqrt{\frac{\eta}{2}} dl_t, \quad d\left(\frac{y}{1+z}\right) = \frac{1}{2} \left(\frac{y_t}{1+z_t}\right) dt + \sqrt{\frac{\eta}{2}} dQ_t$$

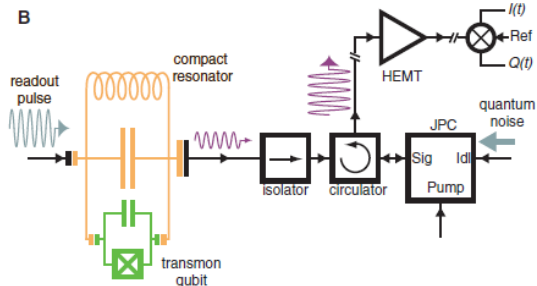
This provides a completion of $\frac{1}{2}(x_t^2 + y_t^2) + c_t(1 + z_t)^2 - (1 + z_t) = 0$ with

$$\frac{x_t}{1+z_t} = e^{t/2} \left(\frac{x_0}{1+z_0} + \sqrt{\frac{\eta}{2}} \int_0^t e^{-\tau/2} dl_\tau \right), \quad \frac{y_t}{1+z_t} = e^{t/2} \left(\frac{y_0}{1+z_0} + \sqrt{\frac{\eta}{2}} \int_0^t e^{-\tau/2} dQ_\tau \right).$$

Related to **Picard-Vessiot and Liouvillian extensions of differential fields**: the solution of the quantum filter is an algebraic function of some integrals and exponentials of integral of its two inputs I_t and Q_t .

⁴Ph. Campagne-Ibarcq et al. PRX 2016.

The second case where the qubit is confined to a deterministic surface⁵



Superconducting qubit dispersively coupled to a cavity traversed by a microwave signal (input/output theory). The back-action on the qubit state of a single measurement of both output field quadratures I_t and Q_t is described by a simple SME for the qubit density operator. (M. Hatridge et al.: Science, 2013).

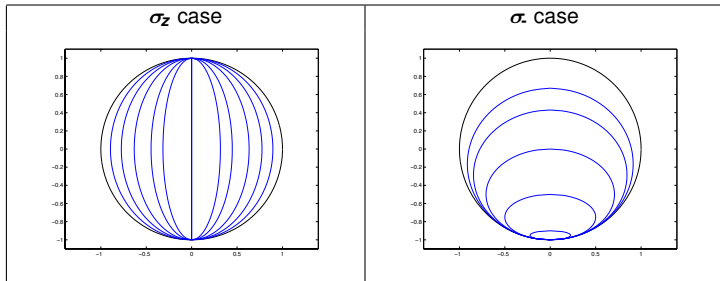
$$d\rho_t = (\gamma(\sigma_z \rho \sigma_z - \rho_t)) dt + \sqrt{\frac{\eta\gamma}{2}} (\sigma_z \rho_t + \rho_t \sigma_z - 2 \text{Tr}(\sigma_z \rho_t) \rho_t) dW_I + i\sqrt{\frac{\eta\gamma}{2}} [\sigma_z, \rho_t] dW_Q$$

with $dI_t = \sqrt{\frac{\eta\gamma}{2}} \text{Tr}(2\sigma_z \rho_t) dt + dW_I$ and $dQ_t = dW_Q$, where $\gamma \geq 0$ is related to the measurement strength and $\eta \in [0, 1]$ is the detection efficiency.

The deterministic surface is given here by another ellipsoid of revolution axis z :

$$x_t^2 + y_t^2 + b_t(z_t^2 - 1) = 0 \text{ where } b_t = b_0 e^{-2(1-\eta)t} \text{ and } b_0 = \frac{x_0^2 + y_0^2}{1 - z_0^2}.$$

⁵A. Sarlette, P.R.: preprint 2016 (arXiv:1603.05402).



Theorem [A. Sarlette, P.R.: arXiv:1603.05402] For any initial state ρ_0 , the qubit state ρ_t , solution of the SME ($\eta_\nu \in (0, 1)$)

$$d\rho_t = \left(\sum_{\nu} L_{\nu} \rho_t L_{\nu}^{\dagger} - \frac{1}{2} (L_{\nu}^{\dagger} L_{\nu} \rho_t + \rho_t L_{\nu}^{\dagger} L_{\nu}) \right) dt + \sum_{\nu} \sqrt{\eta_{\nu}} \left(L_{\nu} \rho_t + \rho_t L_{\nu}^{\dagger} - \text{Tr} \left((L_{\nu} + L_{\nu}^{\dagger}) \rho_t \right) \rho_t \right) dW_{\nu,t},$$

is restricted to a deterministically evolving 2-dimensional manifold if, and only if,

- ▶ either exist $\beta_{\nu}, \alpha_{\nu} \in \mathbb{C}$ and $U \in U(2)$ such that $L_{\nu} = \beta_{\nu} V \sigma_z V^{\dagger} + \alpha_{\nu}$, $\forall \nu$
- ▶ or exist $\beta_{\nu} \in \mathbb{C}$ and $V \in U(2)$ such that $L_{\nu} = \beta_{\nu} V \sigma_x V^{\dagger}$, $\forall \nu$.

Stroock-Varadhan theorem⁶

Consider a stochastic differential equation

$$dx_t = F(x_t) dt + \sum_{j=1}^m G_j(x) \circ dW_t^j,$$

with $x_t \in \mathbb{R}^N$ the state, $dW_t^1, dW_t^2, \dots, dW_t^m$ independent Wiener processes, x_0 fixed and the dynamics to be understood in the Stratonovitch sense (we therefore put the \circ symbol).

The support of the distribution of x_t can be described as the closure, for the natural Banach topology on $C([0, 1], \mathbb{R}^N)$, of the set of solutions of the following controlled system:

$$d\tilde{x}_t = F(\tilde{x}_t) dt + \sum_{j=1}^m G_j(\tilde{x}) du_t^j,$$

with $\tilde{x}_0 = x_0$, for all possible control signals $u_t^1, u_t^2, \dots, u_t^m$ in $H^1([0, 1], \mathbb{R}^m)$.

⁶D.W. Stroock and S.R.S. Varadhan, "On the support of diffusion processes with applications to the strong maximum principle", Proc. 6th Berkeley Symp. Mathematical Statistics and Probability vol.3, pp.333-359, 1972.

- ▶ **Strong accessibility theorem**⁷ *The control system*
 $\frac{d}{dt}x = F(x) + \sum_{j=1}^m \mathbf{G}_j(x) u_j$ with analytic vector fields $F, \mathbf{G}_1, \dots, \mathbf{G}_m$ is strongly accessible at x_0 if, and only if, the **drift-preserved Lie algebra** \mathfrak{G}_F ⁸ has full dimension N at x_0 .
 Moreover, if \mathfrak{G}_F has dimension at most $N - n < N$ for all x_0 , then the system stays on a (time-dependent) manifold of dimension $N - n$, independently of the control inputs.

- ▶ **Stratonovitch form of the SME:**

$$\begin{aligned}
 d\rho_t = & \sum_{\nu} (1 - \eta_{\nu}) \left(L_{\nu} \rho_t L_{\nu}^{\dagger} - \frac{1}{2} (L_{\nu}^{\dagger} L_{\nu} \rho_t + \rho_t L_{\nu}^{\dagger} L_{\nu}) \right) dt \\
 & - \left(\sum_{\nu} \frac{\eta_{\nu}}{2} \left(L_{\nu}^{\dagger} L_{\nu} \rho + \rho L_{\nu}^{\dagger} L_{\nu} + (L_{\nu})^2 \rho + \rho (L_{\nu}^{\dagger})^2 \right) \right) dt \\
 & + \left(\sum_{\nu} \frac{\eta_{\nu}}{2} \text{Tr} \left(L_{\nu}^{\dagger} L_{\nu} \rho + \rho L_{\nu}^{\dagger} L_{\nu} + (L_{\nu})^2 \rho + \rho (L_{\nu}^{\dagger})^2 \right) \rho \right) dt \\
 & + \left(\sum_{\nu} \eta_{\nu} \text{Tr} \left(L_{\nu} \rho + \rho L_{\nu}^{\dagger} \right) (L_{\nu} \rho + \rho L_{\nu}^{\dagger}) - \eta_{\nu} \left(\text{Tr} \left(L_{\nu} \rho + \rho L_{\nu}^{\dagger} \right) \right)^2 \rho \right) dt \\
 & + \sum_{\nu} \sqrt{\eta_{\nu}} \left(L_{\nu} \rho_t + \rho_t L_{\nu}^{\dagger} - \text{Tr} \left((L_{\nu} + L_{\nu}^{\dagger}) \rho_t \right) \rho_t \right) \circ dW_{\nu,t}.
 \end{aligned}$$

⁷A. Isidori, *Nonlinear Control Systems: An Introduction*, Springer, Berlin, 1985

⁸ \mathfrak{G}_F is the smallest Lie algebra containing \mathfrak{G} (the Lie algebra generated by vector fields $\mathbf{G}_1, \mathbf{G}_2, \dots, \mathbf{G}_m$) and closed under Lie brackets with F , i.e. for any $\mathbf{G} \in \mathfrak{G}_F$ we have $[F, \mathbf{G}] \in \mathfrak{G}_F$.

1. Stochastic master equations govern the dynamics of open quantum systems by taking into account **measurement back-action** and **decoherence** (unread measurement).
2. Future work could investigate how general confinement of the density operator to submanifolds is in higher-dimensional Hilbert spaces.
3. Interest of continuous fluorescence signals (dI_t, dQ_t) for the characterization of a dephasing noise ξ_t :

$$dx_t = \left(-\frac{\gamma_2}{2} x_t + \xi_t y_t - v(t) z_t \right) dt + \sqrt{\frac{\eta \gamma_1}{2}} \left((1 + z_t - x_t^2) dW_I - x_t y_t dW_Q \right)$$

$$dy_t = \left(-\xi_t x_t - \frac{\gamma_2}{2} y_t + u(t) z_t \right) dt + \sqrt{\frac{\eta \gamma_1}{2}} \left(-x_t y_t dW_I + (1 + z_t - y_t^2) dW_Q \right)$$

$$dz_t = \left(v(t) x_t - u(t) y_t - \gamma_1 (1 + z_t) \right) dt - \sqrt{\frac{\eta \gamma_1}{2}} (1 + z_t) \left(x_t dW_I + y_t dW_Q \right)$$

$$dI_t = \sqrt{\frac{\eta \gamma_1}{2}} x_t dt + dW_I$$

$$dQ_t = \sqrt{\frac{\eta \gamma_1}{2}} y_t dt + dW_Q$$

where $u(t)$ and $v(t)$ are well chosen open-loop controls (see Lorenza Viola presentation and work).