

Lake Como School of Advanced Studies September 19-23, 2022 Quantum characterization and control of quantum complex systems

Quantum Stochastic Master Equations (SME) based on preprint to appear in Annual Reviews in Control https://arxiv.org/abs/2208.07416

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Dynamics of open quantum systems based on three quantum features $\frac{1}{2}$

1. Schrödinger ($\hbar = 1$): wave funct. $|\psi\rangle \in \mathcal{H}$, density op. $\rho \sim |\psi\rangle\langle\psi|$

$$rac{d}{dt}|\psi
angle = -i\mathbf{H}|\psi
angle, \quad \mathbf{H} = \mathbf{H_0} + u\mathbf{H_1} = \mathbf{H^\dagger}, \quad rac{d}{dt}
ho = -i[\mathbf{H},
ho].$$

- 2. Origin of dissipation: collapse of the wave packet induced by the measurement of $O = O^{\dagger}$ with spectral decomp. $\sum_{y} \lambda_{y} P_{y}$:
 - ► measurement outcome y with proba. $\mathbb{P}_y = \langle \psi | \mathsf{P}_y | \psi \rangle = \operatorname{Tr}(\rho \mathsf{P}_y)$ depending on $|\psi\rangle$, ρ just before the measurement

measurement back-action if outcome y:

$$|\psi\rangle \mapsto |\psi\rangle_{+} = \frac{\mathsf{P}_{y}|\psi\rangle}{\sqrt{\langle \psi|\mathsf{P}_{y}|\psi\rangle}}, \quad \rho \mapsto \rho_{+} = \frac{\mathsf{P}_{y}\rho\mathsf{P}_{y}}{\mathsf{Tr}\left(\rho\mathsf{P}_{y}\right)}$$

- 3. Tensor product for the description of composite systems (S, C):
 - $\blacktriangleright \text{ Hilbert space } \mathcal{H} = \mathcal{H}_s \otimes \mathcal{H}_c$
 - Hamiltonian $H = H_s \otimes I_c + H_{sc} + I_s \otimes H_c$
 - observable on sub-system C only: $O = I_s \otimes O_c$.

¹S. Haroche and J.M. Raimond (2006). *Exploring the Quantum: Atoms, Cavities and Photons.* Oxford Graduate Texts.

PSI 🕷

Diffusive stochastic master equation²



 $t\mapsto
ho_t$ continuous time function (not differentiable), solution of

$$d\rho_t = -i \Big[H_0 + u H_1, \rho_t \Big] dt + \left(\sum_{\nu=d,m} L_{\nu} \rho_t L_{\nu}^{\dagger} - \frac{1}{2} (L_{\nu}^{\dagger} L_{\nu} \rho_t + \rho_t L_{\nu}^{\dagger} L_{\nu}) \right) dt + \dots$$
$$\dots + \sqrt{\eta} \Big(L_m \rho_t + \rho_t L_m^{\dagger} - \operatorname{Tr} (L_m \rho_t + \rho_t L_m^{\dagger}) \rho_t \Big) dW_t,$$

where $\eta \in [0,1]$ and the same Wiener process W_t is shared by the state dynamics and the output map

$$dy_t = \sqrt{\eta} \operatorname{Tr}(L_m \rho_t + \rho_t L_m^{\dagger}) dt + dW_t.$$

²A. Barchielli and M. Gregoratti. *Quantum Trajectories and Measurements in Continuous Time: the Diffusive Case.* Springer Verlag, 2009.

Jump stochastic master equation ³



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 $t\mapsto \rho_t$ piecewise smooth time function, solution of

$$d\rho_{t} = \left(-i[\mathsf{H},\rho_{t}] + \mathsf{V}\rho_{t}\mathsf{V}^{\dagger} - \frac{1}{2}(\mathsf{V}^{\dagger}\mathsf{V}\rho_{t} + \rho_{t}\mathsf{V}^{\dagger}\mathsf{V})\right) dt \\ + \left(\frac{\bar{\theta}\rho_{t} + \bar{\eta}\mathsf{V}\rho_{t}\mathsf{V}^{\dagger}}{\bar{\theta} + \bar{\eta}\mathsf{Tr}(\mathsf{V}\rho_{t}\mathsf{V}^{\dagger})} - \rho_{t}\right) \left(dy_{t} - \left(\bar{\theta} + \bar{\eta}\mathsf{Tr}(\mathsf{V}\rho_{t}\mathsf{V}^{\dagger})\right) dt\right)$$

where $\bar{\theta} \ge 0$ (shot-noise rate) and $\bar{\eta} \in [0,1]$ (detection efficiency) and where the counting detector outcome $dy_t \in \{0,1\}$ with

•
$$dy_t = 0$$
 with probability $1 - (\bar{\theta} + \bar{\eta} \operatorname{Tr} (\nabla \rho_t \nabla^{\dagger})) dt$ and then
 $\rho_{t+dt} = \rho_t + (-i[\mathsf{H}, \rho_t] + \nabla \rho_t \nabla^{\dagger} - \frac{1}{2} (\nabla^{\dagger} \nabla \rho_t + \rho_t \nabla^{\dagger} \nabla) + \bar{\eta} (\operatorname{Tr} (\nabla \rho_t \nabla^{\dagger}) \rho_t - \nabla \rho_t \nabla^{\dagger})) dt$
• $dy_t = 1$ with probability $(\bar{\theta} + \bar{\eta} \operatorname{Tr} (\nabla \rho_t \nabla^{\dagger})) dt$, and then
 $\rho_{t+dt} = \frac{\bar{\theta} \rho_t + \bar{\eta} \nabla \rho_t \nabla^{\dagger}}{\bar{\theta} + \bar{\eta} \operatorname{Tr} (\nabla \rho_t \nabla^{\dagger})}.$

³see, e.g., J. Dalibard, Y. Castin, and K. Mølmer. Wave-function approach to dissipative processes in quantum optics. *Phys. Rev. Lett.*, 68(5):580–583, February 1992.

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LKB photon box⁴



Dispersive qubit/photon interaction: H_{int} = −χ(|e⟩⟨e| − |g⟩⟨g|) ⊗ n (with χ a constant parameter) yields e^{-iTH_{int}}, the Schrödinger propagator during the time T > 0, given with θ = χT by

$$\mathsf{U}_{ heta} = |g
angle\!\langle g|\otimes e^{-i heta \mathsf{n}} + |e
angle\!\langle e|\otimes e^{i heta \mathsf{n}}$$

• resonant qubit/photon interaction: $H_{int} = i \frac{\omega}{2} (|g\rangle\langle e| \otimes a^{\dagger} - |e\rangle\langle g| \otimes a)$ (with ω a constant parameter) yields $e^{-iTH_{int}}$, the Schrödinger propagator during the time T > 0, given with $\theta = \omega T/2$ by

$$\begin{split} \mathsf{U}_{\theta} &= |g\rangle\!\langle g| \otimes \cos(\theta\sqrt{\mathsf{n}}) + |e\rangle\!\langle e| \otimes \cos(\theta\sqrt{\mathsf{n}}+\mathsf{I}) \\ &+ |g\rangle\!\langle e| \otimes \frac{\sin(\theta\sqrt{\mathsf{n}})}{\sqrt{\mathsf{n}}}\mathsf{a}^{\dagger} - |e\rangle\!\langle g| \otimes \mathsf{a}\frac{\sin(\theta\sqrt{\mathsf{n}})}{\sqrt{\mathsf{n}}}. \end{split}$$

⁴LKB for Laboratoire Kastler Brossel.



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Photons measured by dispersive qubits (1)





$$\begin{split} \mathsf{U} &= \left(\left(\left(\frac{|g\rangle - |e\rangle}{\sqrt{2}} \right) \langle g| + \left(\frac{|g\rangle + |e\rangle}{\sqrt{2}} \right) \langle e| \right) \otimes \mathsf{I} \right) \\ & \left(|g\rangle \langle g| \otimes e^{-i\theta \mathsf{n}} + |e\rangle \langle e| \otimes e^{i\theta \mathsf{n}} \right) \\ & \left(\left(\left(\frac{|g\rangle + |e\rangle}{\sqrt{2}} \right) \langle g| + \left(\frac{-|g\rangle + |e\rangle}{\sqrt{2}} \right) \langle e| \right) \otimes \mathsf{I} \right) \end{split}$$

applied on $|\Psi
angle=|g
angle\otimes|\psi
angle$ yields

$$\mathsf{U} \ (|g\rangle|\psi\rangle) = |g\rangle \ \cos(\theta \mathsf{n})|\psi\rangle + |e\rangle \ i\sin(\theta \mathsf{n})|\psi\rangle.$$

Markov process induced by the passage of qubit number k:

$$|\psi_{k+1}\rangle = \begin{cases} \frac{\cos(\theta n)|\psi_k\rangle}{\sqrt{\langle\psi_k|\cos^2(\theta n)|\psi_k\rangle}} & \text{if } y_k = g \text{ with probability } \langle\psi_k|\cos^2(\theta n)|\psi_k\rangle ;\\ \frac{i\sin(\theta n)|\psi_k\rangle}{\sqrt{\langle\psi_k|\sin^2(\theta n)|\psi_k\rangle}} & \text{if } y_k = e \text{ with probability } \langle\psi_k|\sin^2(\theta n)|\psi_k\rangle ;\end{cases}$$

where $y_k \in \{g, e\}$ classical signal produced by measurement of qubit k.

Photons measured by dispersive qubits (2)



The density operator formulation ($\rho\equiv |\psi\rangle\langle\psi|$):

$$\rho_{k+1} = \begin{cases} \frac{\mathsf{M}_{g}\rho_{k}\mathsf{M}_{g}^{\dagger}}{\mathsf{Tr}(\mathsf{M}_{g}\rho_{k}\mathsf{M}_{g}^{\dagger})} & \text{if } y_{k} = g \text{ with probability } \mathsf{Tr}\left(\mathsf{M}_{g}\rho_{k}\mathsf{M}_{g}^{\dagger}\right); \\ \frac{\mathsf{M}_{e}\rho_{k}\mathsf{M}_{e}^{\dagger}}{\mathsf{Tr}(\mathsf{M}_{e}\rho_{k}\mathsf{M}_{e}^{\dagger})} & \text{if } y_{k} = e \text{ with probability } \mathsf{Tr}\left(\mathsf{M}_{e}\rho_{k}\mathsf{M}_{e}^{\dagger}\right); \end{cases}$$

with measurement Kraus operators $M_g = \cos(\theta n)$ and $M_e = \sin(\theta n)$. Notice that $M_g^{\dagger}M_g + M_e^{\dagger}M_e = I$.

For θ/π irrational, almost sure convergence towards a Fock state $|\bar{n}\rangle\langle\bar{n}|$ for some \bar{n} based on the Lyapunov function (super-martingale)

$$V(\rho) = \sum_{0 \le n_1 < n_2} \sqrt{\langle n_1 | \rho | n_1 \rangle \langle n_2 | \rho | n_2 \rangle}$$

that converges in average towards 0 since

$$\mathbb{E}\left(V(\rho_{k+1}) \mid \rho_k\right) \leq \left(\max_{0 \leq n_1 < n_2} |\cos(\theta(n_1 \pm n_2)|) \quad V(\rho_k).$$

Probability that a realisation converges towards $|\bar{n}\rangle\langle\bar{n}|$ given by its initial population $\langle\bar{n}|\rho_0|\bar{n}\rangle$



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Photons measured by resonant qubits (1)





Wave function $|\Psi\rangle$ of the composite qubit/photon system just before D:

$$\begin{split} \left(|g\rangle\langle g|\cos(\theta\sqrt{n}) + |e\rangle\langle e|\cos(\theta\sqrt{n}+1) \\ + |g\rangle\langle e|\frac{\sin(\theta\sqrt{n})}{\sqrt{n}}a^{\dagger} - |e\rangle\langle g|a\frac{\sin(\theta\sqrt{n})}{\sqrt{n}}\right)|g\rangle|\psi\rangle \\ = |g\rangle \ \cos(\theta\sqrt{n})|\psi\rangle - |e\rangle \ a\frac{\sin(\theta\sqrt{n})}{\sqrt{n}}|\psi\rangle \end{split}$$

Resulting Markov process associated to the measurement of the observable $\sigma_z = |e\rangle\langle e| - |g\rangle\langle g|$ with classical output signal $y \in \{g, e\}$:

$$|\psi_{k+1}\rangle = \begin{cases} \frac{\cos(\theta\sqrt{n})|\psi_k\rangle}{\sqrt{\langle\psi_k|\cos^2(\theta\sqrt{n})|\psi_k\rangle}} & \text{if } y_k = g \text{ with probability } \langle\psi_k|\cos^2(\theta\sqrt{n})|\psi_k\rangle ; \\ -\frac{a\frac{\sin(\theta\sqrt{n})}{\sqrt{n}}|\psi_k\rangle}{\sqrt{\langle\psi_k|\sin^2(\theta\sqrt{n})|\psi_k\rangle}} & \text{if } y_k = e \text{ with probability } \langle\psi_k|\sin^2(\theta\sqrt{n})|\psi_k\rangle ; \\ \frac{11/53}{\sqrt{\langle\psi_k|\sin^2(\theta\sqrt{n})|\psi_k\rangle}} & \frac{11/53}{\sqrt{\langle\psi_k|\sin^2(\theta\sqrt{n})|\psi_k\rangle}} \end{cases}$$

Density operator formulation;

$$\rho_{k+1} = \begin{cases} \frac{\mathsf{M}_{g}\rho_{k}\mathsf{M}_{g}^{\dagger}}{\mathsf{Tr}(\mathsf{M}_{g}\rho_{k}\mathsf{M}_{g}^{\dagger})} & \text{if } y_{k} = g \text{ with probability } \mathsf{Tr}\left(\mathsf{M}_{g}\rho_{k}\mathsf{M}_{g}^{\dagger}\right); \\ \frac{\mathsf{M}_{e}\rho_{k}\mathsf{M}_{e}^{\dagger}}{\mathsf{Tr}(\mathsf{M}_{e}\rho_{k}\mathsf{M}_{e}^{\dagger})} & \text{if } y_{k} = e \text{ with probability } \mathsf{Tr}\left(\mathsf{M}_{e}\rho_{k}\mathsf{M}_{e}^{\dagger}\right); \end{cases}$$

with measurement Kraus operators $M_g = \cos(\theta \sqrt{n})$ and $M_e = a \frac{\sin(\theta \sqrt{n})}{\sqrt{n}}$. Notice that, once again, $M_g^{\dagger}M_g + M_e^{\dagger}M_e = I$.

For $\theta \sqrt{n}/\pi$ irrational for all *n*, almost surely towards vacuum state $|0\rangle\langle 0|$. Results from the following the Lyapunov function (super-martingale)

$$V(
ho) = \operatorname{Tr}(n
ho)$$

since

$$\mathbb{E}\left(V(\rho_{k+1}) \mid \rho_k\right) = V(\rho_k) - \operatorname{Tr}\left(\sin^2(\theta\sqrt{n})\rho_k\right).$$





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With measurement imperfections, use Bayes rule by taking as quantum state, the expectation value of ρ_{k+1} knowing ρ_k and the information provides by the imperfect measurement outcome.

Assume detector D broken. From

$$\rho_{k+1} = \begin{cases} \frac{\mathsf{M}_{g}\rho_{k}\mathsf{M}_{g}^{\dagger}}{\mathsf{Tr}(\mathsf{M}_{g}\rho_{k}\mathsf{M}_{g}^{\dagger})} & \text{if } y_{k} = g \text{ with probability } \mathsf{Tr}\left(\mathsf{M}_{g}\rho_{k}\mathsf{M}_{g}^{\dagger}\right); \\ \frac{\mathsf{M}_{e}\rho_{k}\mathsf{M}_{e}^{\dagger}}{\mathsf{Tr}\left(\mathsf{M}_{e}\rho_{k}\mathsf{M}_{e}^{\dagger}\right)} & \text{if } y_{k} = e \text{ with probability } \mathsf{Tr}\left(\mathsf{M}_{e}\rho_{k}\mathsf{M}_{e}^{\dagger}\right); \end{cases}$$

we get the quantum channel:

$$\rho_{k+1} = \mathcal{K}(\rho_k) \triangleq \mathbb{E}\left(\rho_{k+1} \mid \rho_k\right) = \mathsf{M}_g \rho_k \mathsf{M}_g^{\dagger} + \mathsf{M}_e \rho_k \mathsf{M}_e^{\dagger}.$$



When the qubit detector D, producing the classical measurement signal $y_k \in \{g, e\}$, has errors characterized by the error rate $\eta_e \in (0, 1)$ (resp. $\eta_g \in (0, 1)$) the probability of detector outcome g (resp. e) knowing that the perfect outcome is e (resp. g), Bayes law gives directly

$$\rho_{k+1} = \begin{cases} \mathbb{E}\left(\rho_{k+1} \mid y_k = g, \rho_k\right) = \frac{(1-\eta_g)\mathsf{M}_g\rho_k\mathsf{M}_g^{\dagger} + \eta_e\mathsf{M}_e\rho_k\mathsf{M}_e^{\dagger}}{\mathsf{Tr}((1-\eta_g)\mathsf{M}_g\rho_k\mathsf{M}_g^{\dagger} + \eta_e\mathsf{M}_e\rho_k\mathsf{M}_e^{\dagger})} \\ \text{with probability } \mathbb{P}(y_k = g|\rho_k) = \mathsf{Tr}\left((1-\eta_g)\mathsf{M}_g\rho_k\mathsf{M}_g^{\dagger} + \eta_e\mathsf{M}_e\rho_k\mathsf{M}_e^{\dagger}\right), \\ \mathbb{E}\left(\rho_{k+1} \mid y_k = e, \rho_k\right) = \frac{\eta_g\mathsf{M}_g\rho_k\mathsf{M}_g^{\dagger} + (1-\eta_e)\mathsf{M}_e\rho_k\mathsf{M}_e^{\dagger}}{\mathsf{Tr}(\eta_g\mathsf{M}_g\rho_k\mathsf{M}_g^{\dagger} + (1-\eta_e)\mathsf{M}_e\rho_k\mathsf{M}_e^{\dagger})} \\ \text{with probability } \mathbb{P}(y_k = e|\rho_k) = \mathsf{Tr}\left(\eta_g\mathsf{M}_g\rho_k\mathsf{M}_g^{\dagger} + (1-\eta_e)\mathsf{M}_e\rho_k\mathsf{M}_e^{\dagger}\right) \end{cases}$$

Notice that a broken detector corresponds to $\eta_e=\eta_g=1/2$ and one recovers the above quantum channel.



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General structure of discrete-time SME based on a quantum channel with the following Kraus decomposition (which is not unique)

$$\mathcal{K}(
ho) = \sum_{\mu} \mathsf{M}_{\mu}
ho \mathsf{M}_{\mu}^{\dagger} \quad ext{where } \sum_{\mu} \mathsf{M}_{\mu}^{\dagger} \mathsf{M}_{\mu} = \mathsf{I}$$

and a left stochastic matrix $(\eta_{y,\mu})$ where y corresponds to the different imperfect measurement outcomes. With $\mathcal{K}_{y}(\rho) = \sum_{\mu} \eta_{y,\mu} \mathsf{M}_{\mu} \rho \mathsf{M}_{\mu}^{\dagger}$, ones gets the following SME:

$$ho_{k+1} = rac{\mathcal{K}_{y_k}(
ho_k)}{\mathsf{Tr}\left(\mathcal{K}_{y_k}(
ho_k)
ight)}$$
 where $y_k = y$ with probability $\mathsf{Tr}\left(\mathcal{K}_y(
ho_k)
ight)$

Notice that $\mathcal{K} = \sum_{y} \mathcal{K}_{y}$ since η is left stochastic.

Here the Hilbert space \mathcal{H} is arbitrary and can be of infinite dimension, the Kraus operator M_{μ} are bounded operator on \mathcal{H} and ρ is a density operator on \mathcal{H} (Hermitian, trace-class with trace one, non-negative). When the index y or μ are continuous, discrete sums are replaced by integrals and probabilities by probability densities.



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Qubits measured by dispersive photons (discrete-time) (1)



Probe photon in the coherent state $|i\frac{\alpha}{\sqrt{2}}\rangle$ with $\alpha > 0$. Just before D the composite qubit/photon wave function $|\Psi\rangle$ reads:

$$\left(|g\rangle\langle g|e^{-i\theta n} + |e\rangle\langle e|e^{i\theta n}\right)|\psi\rangle|i\frac{\alpha}{\sqrt{2}}\rangle = \langle g|\psi\rangle|g\rangle|ie^{-i\theta}\frac{\alpha}{\sqrt{2}}\rangle + \langle e|\psi\rangle|e\rangle|ie^{i\theta}\frac{\alpha}{\sqrt{2}}\rangle.$$

Measurement outcome $y \in \mathbb{R}$ corresponding to observable

$$\mathsf{Q} = rac{\mathsf{a} + \mathsf{a}^\dagger}{\sqrt{2}} \equiv \int_{-\infty}^{+\infty} q |q
angle \! \langle q | dq ext{ where } \langle q | q'
angle = \delta(q-q').$$

Since $|ie^{\pm i\theta}\frac{\alpha}{\sqrt{2}}\rangle = \frac{1}{\pi^{1/4}}\int_{-\infty}^{+\infty}e^{iq\alpha\cos\theta}e^{-\frac{(q\pm\alpha\sin\theta)^2}{2}}|q\rangle dq$, we have

$$\begin{split} \langle g | \psi \rangle | g \rangle & |ie^{-i\theta} \frac{\alpha}{\sqrt{2}} \rangle + \langle e | \psi \rangle | e \rangle & |ie^{i\theta} \frac{\alpha}{\sqrt{2}} \rangle \\ = \frac{1}{\pi^{1/4}} \int_{-\infty}^{+\infty} e^{iq\alpha \cos\theta} \left(e^{-\frac{(q-\alpha \sin\theta)^2}{2}} \langle g | \psi \rangle | g \rangle + e^{-\frac{(q+\alpha \sin\theta)^2}{2}} \langle e | \psi \rangle | e \rangle \right) | q \rangle dq. \end{split}$$

Thus

$$\begin{split} |\psi_{k+1}\rangle &= e^{iy_k\alpha\cos\theta} \frac{e^{-\frac{(y_k-\alpha\sin\theta)^2}{2}} \langle g | \psi_k \rangle | g \rangle + e^{-\frac{(y_k+\alpha\sin\theta)^2}{2}} \langle e | \psi_k \rangle | e \rangle}{\sqrt{e^{-(y_k-\alpha\sin\theta)^2} |\langle g | \psi_k \rangle |^2 + e^{-(y_k+\alpha\sin\theta)^2} |\langle e | \psi_k \rangle |^2}} \\ \text{where } y_k \in [y, y + dy] \text{ with prob. } \frac{e^{-(y-\alpha\sin\theta)^2} |\langle g | \psi_k \rangle |^2 + e^{-(y+\alpha\sin\theta)^2} |\langle e | \psi_k \rangle |^2}{\sqrt{\pi}} dy. \end{split}$$

Qubits measured by dispersive photons (discrete-time) (2)



Density operator formulation

$$\rho_{k+1} = \frac{\mathsf{M}_{y_k}\rho_k\mathsf{M}_{y_k}^{\dagger}}{\mathsf{Tr}\left(\mathsf{M}_{y_k}\rho_k\mathsf{M}_{y_k}^{\dagger}\right)} \quad \text{where } y_k \in [y, y + dy] \text{ with probability } \mathsf{Tr}\left(\mathsf{M}_y\rho_k\mathsf{M}_y^{\dagger}\right) dy$$

and measurement Kraus operators

$$\mathsf{M}_{y} = \frac{1}{\pi^{1/4}} e^{-\frac{(y-\alpha\sin\theta)^{2}}{2}} |g\rangle \langle g| + \frac{1}{\pi^{1/4}} e^{-\frac{(y+\alpha\sin\theta)^{2}}{2}} |e\rangle \langle e|.$$

Notice that

$$\mathsf{Tr}\left(\mathsf{M}_{y}\rho\mathsf{M}_{y}^{\dagger}\right) = \frac{1}{\sqrt{\pi}} e^{-(y-\alpha\sin\theta)^{2}} \langle g|\rho|g\rangle + \frac{1}{\sqrt{\pi}} e^{-(y+\alpha\sin\theta)^{2}} \langle e|\rho|e\rangle$$

and $\int_{-\infty}^{+\infty} M_y^{\dagger} M_y \, dy = |g\rangle \langle g| + |e\rangle \langle e| = I$. For $\alpha \neq 0$, almost sure convergence towards $|g\rangle$ or $|e\rangle$ deduced from Lyapunov function

$$V(
ho) = \sqrt{\langle g |
ho | g \rangle \langle e |
ho | e
angle}$$
 with $\mathbb{E} \left(V(
ho_{k+1}) \mid
ho_k \right) = e^{-lpha^2 \sin^2 heta} V(
ho_k)$

Qubits measured by dispersive photons (discrete-time) (3)



Detection imperfections: probability density of y knowing perfect detection q is a Gaussian given by $\frac{1}{\sqrt{\pi\sigma}}e^{-\frac{(y-q)^2}{\sigma}}$ for some error parameter $\sigma > 0$. Then the above Markov process becomes

$$\rho_{k+1} = \frac{\mathcal{K}_{y_k}(\rho_k)}{\operatorname{Tr}\left(\mathcal{K}_{y_k}(\rho_k)\right)}$$

where

$$\mathcal{K}_{\mathcal{Y}}(
ho) = \int_{-\infty}^{\infty} rac{1}{\sqrt{\pi\sigma}} e^{-rac{(\mathcal{Y}-q)^2}{\sigma}} \mathsf{M}_q
ho \mathsf{M}_q^\dagger \; dq$$

Standard computations using

$$\mathsf{M}_q = \frac{1}{\pi^{1/4}} e^{-\frac{(q-\alpha\sin\theta)^2}{2}} |g\rangle \langle g| + \frac{1}{\pi^{1/4}} e^{-\frac{(q+\alpha\sin\theta)^2}{2}} |e\rangle \langle e|$$

show that

$$\mathcal{K}_{\mathcal{Y}}(
ho) = rac{1}{\sqrt{\pi(1+\sigma)}} \left(e^{-rac{(y-lpha\sin heta)^2}{1+\sigma}} \langle g|
ho|g
angle |g
angle g| + e^{-rac{(y+lpha\sin heta)^2}{1+\sigma}} \langle e|
ho|e
angle |e
angle |e| + e^{-rac{y^2}{1+\sigma} - (lpha\sin heta)^2} (\langle e|
ho|g
angle |e
angle g| + \langle g|
ho|e
angle |g
angle e|)
ight).$$



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Continuous-time diffusive limit (1)



Density operator formulation (perfect detection)

$$\rho_{k+1} = \frac{\mathsf{M}_{y_k}\rho_k \mathsf{M}_{y_k}^{\dagger}}{\mathsf{Tr}\left(\mathsf{M}_{y_k}\rho_k \mathsf{M}_{y_k}^{\dagger}\right)} \quad \text{where } y_k \in [y, y + dy] \text{ with probability } \mathsf{Tr}\left(\mathsf{M}_y\rho_k \mathsf{M}_y^{\dagger}\right) dy$$

and measurement Kraus operators

$$\mathsf{M}_{y} = \tfrac{1}{\pi^{1/4}} e^{-\tfrac{(y-\alpha\sin\theta)^{2}}{2}} |g\rangle\langle g| + \tfrac{1}{\pi^{1/4}} e^{-\tfrac{(y+\alpha\sin\theta)^{2}}{2}} |e\rangle\langle e|.$$

Since

$$\mathbb{E}\left(y_{k} \mid \rho_{k} = \rho\right) \triangleq \overline{y} = -\alpha \sin \theta \; \operatorname{Tr}\left(\sigma_{z}\rho\right), \; \mathbb{E}\left(y_{k}^{2} \mid \rho_{k} = \rho\right) \triangleq \overline{y^{2}} = 1/2 + (\alpha \sin \theta)^{2}.$$

When 0 < $\alpha \sin \theta = \epsilon \ll$ 1, we have up-to third order terms versus ϵy ,

$$\frac{\mathsf{M}_{y}\rho\mathsf{M}_{y}^{\dagger}}{\mathsf{Tr}\left(\mathsf{M}_{y}\rho\mathsf{M}_{y}^{\dagger}\right)} = \frac{(\cosh(\epsilon y) - \sinh(\epsilon y)\sigma_{z})\rho(\cosh(\epsilon y) - \sinh(\epsilon y)\sigma_{z})}{\cosh(2\epsilon y) - \sinh(2\epsilon y)\,\mathsf{Tr}\left(\sigma_{z}\rho\right)}$$
$$\approx \frac{\rho - \epsilon y(\sigma_{z}\rho + \rho\sigma_{z}) + (\epsilon y)^{2}(\rho + \sigma_{z}\rho\sigma_{z})}{1 - 2\epsilon y\,\mathsf{Tr}\left(\sigma_{z}\rho\right) + 2(\epsilon y)^{2}}$$
$$= \rho + (\epsilon y)^{2}\left(\sigma_{z}\rho\sigma_{z} - \rho\right) + \left(\sigma_{z}\rho + \rho\sigma_{z} - 2\,\mathsf{Tr}\left(\sigma_{z}\rho\right)\rho\right)\left(-\epsilon y - 2(\epsilon y)^{2}\,\mathsf{Tr}\left(\sigma_{z}\rho\right)\right).$$

Continuous-time diffusive limit (2)



Replacing
$$\epsilon^2 y^2$$
 by its expectation value one gets, up to third order in ϵy and ϵ :

$$\frac{M_y \rho M_y^{\dagger}}{\text{Tr}\left(M_y \rho M_y^{\dagger}\right)} \approx \rho + \frac{\epsilon^2}{2} \left(\sigma_z \rho \sigma_z - \rho\right) + \left(\sigma_z \rho + \rho \sigma_z - 2 \text{ Tr}\left(\sigma_z \rho\right) \rho\right) \left(-\epsilon y - \epsilon^2 \text{ Tr}\left(\sigma_z \rho\right)\right).$$
Set $\epsilon^2 = 2dt$ and $\epsilon y = -2 \text{ Tr}\left(\sigma_z \rho\right) dt - dW$. Since by construction
 $\mathbb{E}\left(\epsilon y_k \mid \rho_k = \rho\right) = -\epsilon^2 \text{ Tr}\left(\sigma_z \rho\right)$ and $\mathbb{E}\left((\epsilon y_k)^2 \mid \rho_k = \rho\right) = \epsilon^2 + \epsilon^4$
one has $\mathbb{E}\left(dW \mid \rho\right) = 0$ and $\mathbb{E}\left(dW^2 \mid \rho\right) = dt$ up to order 4 versus ϵ . Thus
for dt very small, we recover the following diffusive SME⁵
 $\rho_{t+dt} = \rho_t + dt \left(\sigma_z \rho_t \sigma_z - \rho\right) + \left(\sigma_z \rho_t + \rho_t \sigma_z - 2 \text{ Tr}\left(\sigma_z \rho_t\right) \rho\right) \left(dy_t - 2 \text{ Tr}\left(\sigma_z \rho_t\right) dt\right)$

with $dy_t = 2 \operatorname{Tr}(\sigma_z \rho_t) dt + dW_t$ replacing $-\epsilon y$ and $dy_t^2 = dW_t^2 = dt$ (Ito rules).

 5 Convergence in distribution when $dt\mapsto0^{+}$: tightness property

 $\forall T > \mathbf{0}, \exists M > \mathbf{0}, \forall dt > \mathbf{0}, \forall k, k_1, k_2 \in \{\mathbf{0}, \dots, [T/dt]\}, \mathbb{E}\left(\left\|\rho_{k_1} - \rho_k\right\|^2 \left\|\left\|\rho_{k_2} - \rho_k\right\|^2 \right| \right. \rho_{\mathbf{0}}\right) \leq M(k_1 - k_2) \, dt,$

and (Markov generator) convergence of $\frac{\mathbb{E}\left(f(\rho_{k+1} \mid \rho_k = \rho\right) - f(\rho)}{dt}$ towards $\mathbb{E}\left(df_t \mid \rho_t = \rho\right)/dt$ for any C^2 real function f.

Continuous-time diffusive limit (3)



With measurement errors parameterized by $\sigma >$ 0, the partial Kraus map

$$\mathcal{K}_{\mathcal{Y}}(
ho) = rac{1}{\sqrt{\pi(1+\sigma)}} \left(e^{-rac{(y-\epsilon)^2}{1+\sigma}} \langle g|
ho|g
angle |g
angle g| + e^{-rac{(y+\epsilon)^2}{1+\sigma}} \langle e|
ho|e
angle |e
angle \langle e|
onumber \ + e^{-rac{y^2}{1+\sigma}-\epsilon^2} (\langle e|
ho|g
angle |e
angle g| + \langle g|
ho|e
angle |g
angle \langle e|)
ight)$$

yields $\mathbb{E}\left(y_k \mid \rho_k\right) \triangleq \overline{y} = -\epsilon \operatorname{Tr}(\sigma_z \rho)$ and $\mathbb{E}\left(y_k^2 \mid \rho_k\right) \triangleq \overline{y^2} = (1+\sigma)/2 + \epsilon^2$. Similar approximations with $\epsilon^2 = 2dt$ and dt very small, yield an SME with detection efficiency $\eta = \frac{1}{1+\sigma}$:

$$\rho_{t+dt} = \rho_t + dt \left(\sigma_z \rho_t \sigma_z - \rho\right) + \sqrt{\eta} \left(\sigma_z \rho_t + \rho_t \sigma_z - 2 \operatorname{Tr} \left(\sigma_z \rho_t\right) \rho\right) dW_t$$

with $dy_t = \sqrt{\eta} \operatorname{Tr} (\sigma_z \rho_t + \rho_t \sigma_z) + dW_t \sim -\epsilon y / \sqrt{1 + \sigma}$. Convergence towards either $|g\rangle$ or $|e\rangle$ (QND measurement of the qubit) based on Lyapunov fonction $V(\rho) = \sqrt{1 - \operatorname{Tr} (\sigma_z \rho)^2}$ and Ito rules:

$$dV = -\frac{zdz}{\sqrt{1-z^2}} - \frac{dz^2}{2(1-z^2)^{3/2}} = -\frac{zdz}{\sqrt{1-z^2}} - 2\eta^2 V dt$$

where $z = \operatorname{Tr}(\sigma_{z}\rho)$, $dz = 2\eta(1-z^{2})dW$ and $dz^{2} = 4\eta^{2}(1-z^{2})^{2}dt$. Since $\mathbb{E}\left(dz \mid z\right) = 0$, $\bar{V}_{t} = \mathbb{E}\left(V(z_{t}) \mid z_{0}\right)$ solution of $\frac{d}{dt}\bar{V}_{t} = -2\eta^{2}\bar{V}_{t}$.



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Continuous-time Poisson SME

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Continous-time Wiener/Poisson SME

Conclusion

Diffusive SME⁶



General form of diffusive SME with Ito formulation:

$$d\rho_{t} = \left(-i[\mathsf{H},\rho_{t}] + \sum_{\nu} \mathsf{L}_{\nu}\rho_{t}\mathsf{L}_{\nu}^{\dagger} - \frac{1}{2}(\mathsf{L}_{\nu}^{\dagger}\mathsf{L}_{\nu}\rho_{t} + \rho_{t}\mathsf{L}_{\nu}^{\dagger}\mathsf{L}_{\nu})\right)dt$$
$$+ \sum_{\nu}\sqrt{\eta_{\nu}}\left(\mathsf{L}_{\nu}\rho_{t} + \rho_{t}\mathsf{L}_{\nu}^{\dagger} - \mathsf{Tr}\left((\mathsf{L}_{\nu} + \mathsf{L}_{\nu}^{\dagger})\rho_{t}\right)\rho_{t}\right)dW_{\nu,t},$$
$$dy_{\nu,t} = \sqrt{\eta_{\nu}}\mathsf{Tr}\left(\mathsf{L}_{\nu}\rho_{t} + \rho_{t}\mathsf{L}_{\nu}^{\dagger}\right)dt + dW_{\nu,t}$$

with efficiencies $\eta_{\nu} \in [0, 1]$ and $dW_{\nu, t}$ being independent Wiener processes. Equivalent formulation with Ito rules:

$$\rho_{t+dt} = \frac{\mathsf{M}_{dy_t}\rho_t \mathsf{M}_{dy_t}^{\dagger} + \sum_{\nu} (1-\eta_{\nu})\mathsf{L}_{\nu}\rho_t \mathsf{L}_{\nu}^{\dagger} dt}{\mathsf{Tr}\left(\mathsf{M}_{dy_t}\rho_t \mathsf{M}_{dy_t}^{\dagger} + \sum_{\nu} (1-\eta_{\nu})\mathsf{L}_{\nu}\rho_t \mathsf{L}_{\nu}^{\dagger} dt\right)}$$

with $M_{dy_t} = I + \left(-iH - \frac{1}{2}\sum_{\nu}L_{\nu}^{\dagger}L_{\nu}\right)dt + \sum_{\nu}\sqrt{\eta_{\nu}}dy_{\nu,t}L_{\nu}$. Moreover $dy_{\nu,t} = s_{\nu,t}\sqrt{dt}$ follows the following probability density knowing ρ_t :

$$\mathbb{P}\Big(\underbrace{(s_{\nu,t} \in [s_{\nu}, s_{\nu} + ds_{\nu}])_{\nu} \mid \rho_t}_{-} = \mathsf{Tr}\left(\mathsf{M}_{s\sqrt{dt}} \; \rho_t \mathsf{M}_{s\sqrt{dt}}^{\dagger} + \sum_{\nu} (1 - \eta_{\nu})\mathsf{L}_{\nu}\rho_t \mathsf{L}_{\nu}^{\dagger} dt\right) \prod_{\nu} \frac{e^{-\frac{s_{\nu}^2}{2}} ds_{\nu}}{\sqrt{2\pi}}$$

⁶A. Barchielli and M. Gregoratti. *Quantum Trajectories and Measurements in Continuous Time: the Diffusive Case*. Springer Verlag, 2009.



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Conclusion

Kraus maps and numerical schemes for diffusive SME⁷



Linearity/positivity/trace preserving numerical integration scheme for

$$\begin{split} d\rho_t &= \left(-i[\mathsf{H},\rho_t] + \sum_{\nu} \mathsf{L}_{\nu}\rho_t \mathsf{L}_{\nu}^{\dagger} - \frac{1}{2}(\mathsf{L}_{\nu}^{\dagger}\mathsf{L}_{\nu}\rho_t + \rho_t\mathsf{L}_{\nu}^{\dagger}\mathsf{L}_{\nu})\right) dt \\ &+ \sum_{\nu} \sqrt{\eta_{\nu}} \left(\mathsf{L}_{\nu}\rho_t + \rho_t\mathsf{L}_{\nu}^{\dagger} - \ \mathsf{Tr}\left((\mathsf{L}_{\nu} + \mathsf{L}_{\nu}^{\dagger})\rho_t\right)\rho_t\right) dW_{\nu,t}, \\ dy_{\nu,t} &= \sqrt{\eta_{\nu}} \ \mathsf{Tr}\left(\mathsf{L}_{\nu}\rho_t + \rho_t\mathsf{L}_{\nu}^{\dagger}\right) dt + dW_{\nu,t} \\ \text{With } \mathsf{M}_0 &= \mathsf{I} + \left(-i\mathsf{H} - \frac{1}{2}\sum_{\nu}\mathsf{L}_{\nu}^{\dagger}\mathsf{L}_{\nu}\right) dt, \quad \mathsf{S} = \mathsf{M}_0^{\dagger}\mathsf{M}_0 + \left(\sum_{\nu}\mathsf{L}_{\nu}^{\dagger}\mathsf{L}_{\nu}\right) dt \ \mathsf{set} \\ \widetilde{\mathsf{M}}_0 &= \mathsf{M}_0\mathsf{S}^{-1/2}, \quad \widetilde{\mathsf{L}}_{\nu} = \mathsf{L}_{\nu}\mathsf{S}^{-1/2}. \end{split}$$

Sampling of $dy_{
u,t}=s_{
u,t}\sqrt{dt}$ according to the following probability law:

$$\mathbb{P}\Big(\left(\textbf{\textit{s}}_{\nu,t}\in[\textbf{\textit{s}}_{\nu},\textbf{\textit{s}}_{\nu}+\textbf{\textit{ds}}_{\nu}]\right)_{\nu}\mid\rho_{t}\Big)=\ \mathsf{Tr}\left(\widetilde{\mathsf{M}}_{s\sqrt{dt}}\rho_{t}\widetilde{\mathsf{M}}_{s\sqrt{dt}}^{\dagger}+\sum_{\nu}(1-\eta_{\nu})\widetilde{\mathsf{L}}_{\nu}\rho_{t}\widetilde{\mathsf{L}}_{\nu}^{\dagger}\textbf{\textit{d}}t\right)\prod_{\nu}\frac{e^{-\frac{s_{\nu}^{2}}{2}}\textbf{\textit{ds}}_{\nu}}{\sqrt{2\pi}}.$$

where $\widetilde{M}_{dy_t} = \widetilde{M}_0 + \sum_{\nu} \sqrt{\eta_{\nu}} dy_{\nu,t} \widetilde{L}_{\nu}$. Exact Kraus-map formulation:

$$\rho_{t+dt} = \frac{\widetilde{\mathsf{M}}_{dy_t}\rho_t \widetilde{\mathsf{M}}_{dy_t}^{\dagger} + \sum_{\nu} (1-\eta_{\nu}) \widetilde{\mathsf{L}}_{\nu} \rho_t \widetilde{\mathsf{L}}_{\nu}^{\dagger} dt}{\mathsf{Tr}\left(\widetilde{\mathsf{M}}_{dy_t} \rho_t \widetilde{\mathsf{M}}_{dy_t}^{\dagger} + \sum_{\nu} (1-\eta_{\nu}) \widetilde{\mathsf{L}}_{\nu} \rho_t \widetilde{\mathsf{L}}_{\nu}^{\dagger} dt\right)}$$

 ⁷A. Jordan, A. Chantasri, PR, and B. Huard. Anatomy of fluorescence: quantum trajectory statistics from continuously measuring spontaneous emission. *Quantum Studies: Mathematics and Foundations*, 3(3):237-263, 2016.



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Qubits measured by photons (resonant) (1)



Probe photon is in the vacuum state $|0\rangle.$ Composite qubit/photon wave function $|\Psi\rangle$ before D:

$$\begin{pmatrix} |g\rangle\langle g|\cos(\theta\sqrt{n}) + |e\rangle\langle e|\cos(\theta\sqrt{n+1}) \\ + |g\rangle\langle e|\frac{\sin(\theta\sqrt{n})}{\sqrt{n}}a^{\dagger} - |e\rangle\langle g|a\frac{\sin(\theta\sqrt{n})}{\sqrt{n}} \end{pmatrix} |\psi\rangle|0\rangle \\ = \left(\langle g|\psi\rangle|g\rangle + \cos\theta\langle e|\psi\rangle|e\rangle\right)|0\rangle + \sin\theta\langle e|\psi\rangle|g\rangle|1\rangle.$$

With measurement observable $n = \sum_{n \ge 0} n |n\rangle\langle n|$, outcome $y \in \{0, 1\}$ reads (density operator formulation)

$$\rho_{k+1} = \begin{cases} \frac{\mathsf{M}_0 \rho_k \mathsf{M}_0^{\dagger}}{\mathsf{Tr}(\mathsf{M}_0 \rho_k \mathsf{M}_0^{\dagger})} & \text{if } y_k = 0 \text{ with probability } \mathsf{Tr}\left(\mathsf{M}_0 \rho_k \mathsf{M}_0^{\dagger}\right); \\ \frac{\mathsf{M}_1 \rho_k \mathsf{M}_1^{\dagger}}{\mathsf{Tr}(\mathsf{M}_1 \rho_k \mathsf{M}_1^{\dagger})} & \text{if } y_k = 1 \text{ with probability } \mathsf{Tr}\left(\mathsf{M}_1 \rho_k \mathsf{M}_1^{\dagger}\right); \end{cases}$$

measurement Kraus operators $M_0 = |g\rangle\langle g| + \cos \theta |e\rangle\langle e|$ and $M_1 = \sin \theta |g\rangle\langle e|$. Almost convergence analysis when $\cos^2(\theta) < 1$ towards $|g\rangle$ via the Lyapunov function (super martingale)

$$V(
ho) = \operatorname{Tr}(|e \rangle \langle e|
ho) \text{ since } \mathbb{E}\left(V(
ho_{k+1}) \mid
ho_k\right) = \cos^2 \theta \ V(
ho_k).$$



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Conclusion

Towards jump SME (1)

Since
$$\operatorname{Tr}\left(\mathsf{M}_{0}\rho\mathsf{M}_{0}^{\dagger}\right) = 1 - \sin^{2}\theta \operatorname{Tr}\left(\sigma\rho\sigma_{+}\right)$$
 and
 $\operatorname{Tr}\left(\mathsf{M}_{1}\rho\mathsf{M}_{1}^{\dagger}\right) = \sin^{2}\theta \operatorname{Tr}\left(\sigma\rho\sigma_{+}\right)$, one gets with $\sin^{2}\theta = dt$ and $y \sim dN$, an
 SME driven by Poisson process $dN_{t} \in \{0,1\}$ of expectation value
 $\operatorname{Tr}\left(\sigma\rho_{t}\sigma_{+}\right)dt$ knowing ρ_{t} :

$$d\rho_{t} = \left(\sigma \rho_{t}\sigma_{+} - \frac{1}{2}(\sigma_{+}\sigma \rho_{t} + \rho_{t}\sigma_{+}\sigma)\right) dt \\ + \left(\frac{\sigma \rho_{t}\sigma_{+}}{\mathsf{Tr}(\sigma \rho_{t}\sigma_{+})} - \rho_{t}\right) \left(dN_{t} - \left(\mathsf{Tr}(\sigma \rho_{t}\sigma_{+})\right) dt\right).$$

At each time-step, one has the following choice:

• with probabilty $1 - \text{Tr}(\sigma_{-}\rho_{t}\sigma_{+}) dt$, $dN_{t} = N_{t+dt} - N_{t} = 0$ and

$$\rho_{t+dt} = \frac{\mathsf{M}_{0}\rho_{t}\mathsf{M}_{0}^{\dagger}}{\mathsf{Tr}\left(\mathsf{M}_{0}\rho_{t}\mathsf{M}_{0}^{\dagger}\right)}$$

with $M_0 = I - \frac{dt}{2}\sigma_+ \sigma$. We with probability $\operatorname{Tr}(\sigma \rho_t \sigma_+) dt$, $dN_t = N_{t+dt} - N_t = 1$ and $\rho_{t+dt} = \frac{M_1 \rho_t M_1^{\dagger}}{\operatorname{Tr}(M_1 \rho_t M_1^{\dagger})}$

with $M_1 = \sqrt{dt} \sigma$.

PSI 🕷

Towards jump SME (2)

INES PARIS

With left stochastic matrix $\begin{pmatrix} 1 - \overline{\theta} dt & 1 - \overline{\eta} \\ \overline{\theta} dt & \overline{\eta} \end{pmatrix}$ including shot noise of rate $\overline{\theta} \ge 0$ and detection efficiency $\overline{\eta} \in [0, 1]$: $dN_t = N_{t+dt} - N_t = 0$ and

$$\begin{split} \rho_{t+dt} &= \frac{(1-\bar{\theta}dt)\mathsf{M}_0\rho_t\mathsf{M}_0^{\dagger} + (1-\bar{\eta})\mathsf{M}_1\rho_t\mathsf{M}_1^{\dagger}}{\mathsf{Tr}\left((1-\bar{\theta}dt)\mathsf{M}_0\rho_t\mathsf{M}_0^{\dagger} + (1-\bar{\eta})\mathsf{M}_1\rho_t\mathsf{M}_1^{\dagger}\right)} \\ &= \frac{\mathsf{M}_0\rho_t\mathsf{M}_0^{\dagger} + (1-\bar{\eta})\mathsf{M}_1\rho_t\mathsf{M}_1^{\dagger}}{\mathsf{Tr}\left(\mathsf{M}_0\rho_t\mathsf{M}_0^{\dagger} + (1-\bar{\eta})\mathsf{M}_1\rho_t\mathsf{M}_1^{\dagger}\right)} + O(dt^2). \end{split}$$

with probability

$$\begin{split} &1 - \left(\bar{\theta} + \bar{\eta} \operatorname{Tr} \left(\sigma \, \rho_t \, \sigma_+ \right) \right) dt = \operatorname{Tr} \left((1 - \bar{\theta} dt) \mathsf{M}_0 \rho_t \mathsf{M}_0^{\dagger} + (1 - \bar{\eta}) \mathsf{M}_1 \rho_t \mathsf{M}_1^{\dagger} \right) + O(dt^2) \\ & \text{and where } \mathsf{M}_0 = \mathsf{I} - \frac{dt}{2} \sigma_+ \sigma \text{ and } \mathsf{M}_1 = \sqrt{dt} \sigma . \\ & dN_t = N_{t+dt} - N_t = 1 \text{ and} \end{split}$$

$$\rho_{t+dt} = \frac{\bar{\theta} \, dt \, \mathsf{M}_0 \rho_t \mathsf{M}_0^{\dagger} + \bar{\eta} \mathsf{M}_1 \rho_t \mathsf{M}_1^{\dagger}}{\mathsf{Tr} \left(\bar{\theta} \, dt \, \mathsf{M}_0 \rho_t \mathsf{M}_0^{\dagger} + \bar{\eta} \mathsf{M}_1 \rho_t \mathsf{M}_1^{\dagger} \right)} = \frac{\bar{\theta} \rho_t + \bar{\eta} \sigma_t \rho_t \sigma_+}{\bar{\theta} + \bar{\eta} \, \mathsf{Tr} \left(\sigma_t \sigma_t \sigma_+ \right)} + O(dt)$$

with probability

$$(\bar{\theta} + \bar{\eta} \operatorname{Tr} (\sigma \rho_t \sigma_{+})) dt = \operatorname{Tr} \left(\bar{\theta} dt \operatorname{M}_0 \rho_t \operatorname{M}_0^{\dagger} + \bar{\eta} \operatorname{M}_1 \rho_t \operatorname{M}_1^{\dagger} \right) + O(dt^2)$$

$$34/53$$

Towards jump SME (3)

MINES PARIS

Jump SME with shot noise rate $ar{ heta}$ and detection efficiency $ar{\eta}$

$$d\rho_{t} = \left(\sigma_{e}\rho_{t}\sigma_{+} - \frac{1}{2}(\sigma_{+}\sigma_{e}\rho_{t} + \rho_{t}\sigma_{+}\sigma_{-})\right) dt \\ + \left(\frac{\bar{\theta}\rho_{t} + \bar{\eta}\sigma_{e}\rho_{t}\sigma_{+}}{\mathsf{Tr}\left(\bar{\theta}\rho_{t} + \bar{\eta}\sigma_{e}\rho_{t}\sigma_{+}\right)} - \rho_{t}\right) \left(dN_{t} - \left(\bar{\theta} + \bar{\eta}\mathsf{Tr}\left(\sigma_{e}\rho_{t}\sigma_{+}\right)\right) dt\right).$$

corresponds to the following choices

$$\blacktriangleright dN_t = N_{t+dt} - N_t = 0$$

$$\rho_{t+dt} = \frac{\mathsf{M}_{0}\rho_{t}\mathsf{M}_{0}^{\dagger} + (1-\bar{\eta})\mathsf{M}_{1}\rho_{t}\mathsf{M}_{1}^{\dagger}}{\mathsf{Tr}\left(\mathsf{M}_{0}\rho_{t}\mathsf{M}_{0}^{\dagger} + (1-\bar{\eta})\mathsf{M}_{1}\rho_{t}\mathsf{M}_{1}^{\dagger}\right)}$$

with probability $1-\left(ar{ heta}+ar{\eta}\; {
m Tr}\left(\sigma_{\!\!-}
ho_t\sigma_{\!\!+}
ight)
ight)dt$,

 $\blacktriangleright \ dN_t = N_{t+dt} - N_t = 1 \text{ and}$

$$\rho_{t+dt} = \frac{\bar{\theta}\rho_t + \bar{\eta}\sigma_{-}\rho_t\sigma_{+}}{\bar{\theta} + \bar{\eta} \operatorname{Tr}\left(\sigma_{-}\rho_t\sigma_{+}\right)}$$

with probability $1 - (\bar{\theta} + \bar{\eta} \operatorname{Tr} (\sigma \rho_t \sigma_+)) dt$, where $M_0 = I - \frac{dt}{2} (\sigma_+ \sigma_- + I)$ and $M_1 = \sqrt{dt} \sigma_-$.



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Jump SME in continuous-time

Continous-time Wiener/Poisson SME

Conclusion

Jump SME in continuous-time⁸ (1)

General structure of a Jump SME in continuous time with counting process N_t with increment expectation value knowing ρ_t given by $\langle dN_t \rangle = \left(\bar{\theta} + \bar{\eta} \operatorname{Tr} \left(V \rho_t V^{\dagger}\right)\right) dt$, with $\bar{\theta} \geq 0$ (shot-noise rate) and $\bar{\eta} \in [0, 1]$ (detection efficiency):

$$\begin{split} d\rho_t &= \left(-i[\mathsf{H},\rho_t] + \mathsf{V}\rho_t\mathsf{V}^{\dagger} - \frac{1}{2}(\mathsf{V}^{\dagger}\mathsf{V}\rho_t + \rho_t\mathsf{V}^{\dagger}\mathsf{V})\right)\,dt \\ &+ \left(\frac{\bar{\theta}\rho_t + \bar{\eta}\mathsf{V}\rho_t\mathsf{V}^{\dagger}}{\bar{\theta} + \bar{\eta}\mathsf{Tr}\left(\mathsf{V}\rho_t\mathsf{V}^{\dagger}\right)} - \rho_t\right)\left(d\mathsf{N}_t - \left(\bar{\theta} + \bar{\eta}\mathsf{Tr}\left(\mathsf{V}\rho_t\mathsf{V}^{\dagger}\right)\right)\,dt\right). \end{split}$$

Here H and V are operators on an underlying Hilbert space H, H being Hermitian. At each time-step between t and t + dt, one has the following recipe

• $dN_t = 0$ with probability $1 - \left(\bar{\theta} + \bar{\eta} \operatorname{Tr}\left(\mathsf{V}\rho_t \mathsf{V}^\dagger\right)\right) dt$

$$\rho_{t+dt} = \frac{\mathsf{M}_{0}\rho_{t}\mathsf{M}_{0}^{\dagger} + (1-\bar{\eta})\mathsf{V}\rho_{t}\mathsf{V}^{\dagger}dt}{\mathsf{Tr}\left(\mathsf{M}_{0}\rho_{t}\mathsf{M}_{0}^{\dagger} + (1-\bar{\eta})\mathsf{V}\rho_{t}\mathsf{V}^{\dagger}dt\right)}$$

where $M_0 = I - (iH + \frac{1}{2}V^{\dagger}V) dt$. $\bullet dN_t = 1$ with probability $(\bar{\theta} + \bar{\eta} \operatorname{Tr} (V\rho_t V^{\dagger})) dt$, $\rho_{t+dt} = \frac{\bar{\theta}\rho_t + \bar{\eta}V\rho_t V^{\dagger}}{\bar{\theta} + \bar{\eta} \operatorname{Tr} (V\rho_t V^{\dagger})}$.



⁸ J. Dalibard, Y. Castin, and K. Mølmer. Wave-function approach to dissipative processes in quantum optics. *Phys. Rev. Lett.*, 68(5):580-583, 1992.



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Continous-time Wiener/Poisson SME

Conclusion

General mixed diffusive/jump SME (1)

Combine in a single SME Wiener and Poisson noises induced by diffusive and counting measurements:

$$d\rho_{t} = \left(-i[\mathsf{H},\rho_{t}] + \mathsf{L}\rho_{t}\mathsf{L}^{\dagger} - \frac{1}{2}(\mathsf{L}^{\dagger}\mathsf{L}\rho_{t} + \rho_{t}\mathsf{L}^{\dagger}\mathsf{L}) + \mathsf{V}\rho_{t}\mathsf{V}^{\dagger} - \frac{1}{2}(\mathsf{V}^{\dagger}\mathsf{V}\rho_{t} + \rho_{t}\mathsf{V}^{\dagger}\mathsf{V})\right) dt + \sqrt{\eta} \left(\mathsf{L}\rho_{t} + \rho_{t}\mathsf{L}^{\dagger} - \mathsf{Tr}\left((\mathsf{L} + \mathsf{L}^{\dagger})\rho_{t}\right)\rho_{t}\right) dW_{t} + \left(\frac{\bar{\theta}\rho_{t} + \bar{\eta}\mathsf{V}\rho_{t}\mathsf{V}^{\dagger}}{\bar{\theta} + \bar{\eta}\mathsf{Tr}\left(\mathsf{V}\rho_{t}\mathsf{V}^{\dagger}\right)} - \rho_{t}\right) \left(d\mathsf{N}_{t} - \left(\bar{\theta} + \bar{\eta}\mathsf{Tr}\left(\mathsf{V}\rho_{t}\mathsf{V}^{\dagger}\right)\right) dt\right)$$

With $dy_t = \sqrt{\eta} \operatorname{Tr} ((L + L^{\dagger}) \rho_t) dt + dW_t$ and $dN_t = 0$ with probability $1 - (\bar{\theta} + \bar{\eta} \operatorname{Tr} (V \rho_t V^{\dagger})) dt$. Kraus-map equivalent formulation:

For $dN_t = 0$ of probability $1 - \left(\bar{\theta} + \bar{\eta} \operatorname{Tr} \left(\mathsf{V} \rho_t \mathsf{V}^{\dagger} \right) \right) dt$

$$\rho_{t+dt} = \frac{\mathsf{M}_{dy_t}\rho_t\mathsf{M}_{dy_t}^{\dagger} + (1-\eta)\mathsf{L}\rho_t\mathsf{L}^{\dagger}dt + (1-\bar{\eta})\mathsf{V}\rho_t\mathsf{V}^{\dagger}dt}{\mathsf{Tr}\left(\mathsf{M}_{dy_t}\rho_t\mathsf{M}_{dy_t}^{\dagger} + (1-\eta)\mathsf{L}\rho_t\mathsf{L}^{\dagger}dt + (1-\bar{\eta})\mathsf{V}\rho_t\mathsf{V}^{\dagger}dt\right)}$$

with $M_{dy_t} = I - (iH + \frac{1}{2}L^{\dagger}L + \frac{1}{2}V^{\dagger}V) dt + \sqrt{\eta}dy_tL$. For $dN_t = 1$ of probability $(\bar{\theta} + \bar{\eta} \operatorname{Tr}(V\rho_tV^{\dagger})) dt$.

$$\rho_{t+dt} = \frac{\mathsf{M}_{dy_t}\tilde{\rho}_t\mathsf{M}_{dy_t}^{\dagger} + (1-\eta)\mathsf{L}\tilde{\rho}_t\mathsf{L}^{\dagger}dt + (1-\bar{\eta})\mathsf{V}\tilde{\rho}_t\mathsf{V}^{\dagger}dt}{\mathsf{Tr}\left(\mathsf{M}_{dy_t}\tilde{\rho}_t\mathsf{M}_{dy_t}^{\dagger} + (1-\eta)\mathsf{L}\tilde{\rho}_t\mathsf{L}^{\dagger}dt + (1-\bar{\eta})\mathsf{V}\tilde{\rho}_t\mathsf{V}^{\dagger}dt\right)} \text{ wit } \mathsf{h} \ \tilde{\rho}_t = \frac{\bar{\theta}\rho_t + \bar{\eta}\mathsf{V}\rho_t\mathsf{V}^{\dagger}}{\bar{\theta} + \bar{\eta}\mathsf{Tr}\left(\mathsf{V}\rho_t\mathsf{V}^{\dagger}\right)}_{39/53}$$



General mixed diffusive/jump SME (2)⁹

+

$$\begin{split} d\rho_{t} &= \left(-i[\mathsf{H},\rho_{t}] + \sum_{\nu}\mathsf{L}_{\nu}\rho_{t}\mathsf{L}_{\nu}^{\dagger} - \frac{1}{2}(\mathsf{L}_{\nu}^{\dagger}\mathsf{L}_{\nu}\rho_{t} + \rho_{t}\mathsf{L}_{\nu}^{\dagger}\mathsf{L}_{\nu}) + \sum_{\mu}\mathsf{V}_{\mu}\rho_{t}\mathsf{V}_{\mu}^{\dagger} - \frac{1}{2}(\mathsf{V}_{\mu}^{\dagger}\mathsf{V}_{\mu}\rho_{t} + \rho_{t}\mathsf{V}_{\mu}^{\dagger}\mathsf{V}_{\mu})\right) \ dt \\ &+ \sum_{\nu}\sqrt{\eta_{\nu}} \left(\mathsf{L}_{\nu}\rho_{t} + \rho_{t}\mathsf{L}_{\nu}^{\dagger} - \operatorname{Tr}\left((\mathsf{L}_{\nu} + \mathsf{L}_{\nu}^{\dagger})\rho_{t}\right)\rho_{t}\right)dW_{\nu,t} \\ &\sum_{\mu} \left(\frac{\bar{\theta}_{\mu}\rho_{t} + \sum_{\mu'}\bar{\eta}_{\mu,\mu'}\mathsf{V}_{\mu'}\rho_{t}\mathsf{V}_{\mu'}^{\dagger}}{\bar{\theta}_{\mu} + \sum_{\mu'}\bar{\eta}_{\mu,\mu'}} \operatorname{Tr}\left(\mathsf{V}_{\mu'}\rho_{t}\mathsf{V}_{\mu'}^{\dagger}\right) - \rho_{t}\right) \left(d\mathsf{N}_{\mu,t} - \left(\bar{\theta}_{\mu} + \sum_{\mu'}\bar{\eta}_{\mu,\mu'}\operatorname{Tr}\left(\mathsf{V}_{\mu'}\rho_{t}\mathsf{V}_{\mu'}^{\dagger}\right)\right)dt\right) \end{split}$$

where $\eta_{\nu} \in [0, 1]$, $\bar{\theta}_{\mu}, \bar{\eta}_{\mu,\mu'} \ge 0$ with $\bar{\eta}_{\mu'} = \sum_{\mu} \bar{\eta}_{\mu,\mu'} \le 1$. The equivalent Kraus-map formulation When $\forall \mu, dN_{\mu,t} = 0$ (probability $1 - \sum_{\mu} \left(\bar{\theta}_{\mu} + \bar{\eta}_{\mu} \operatorname{Tr} \left(V_{\mu} \rho_t V_{\mu}^{\dagger} \right) \right) dt$) we have

$$\rho_{t+dt} = \frac{\mathsf{M}_{dy_t}\rho_t\mathsf{M}_{dy_t}^{\dagger} + \sum_{\nu}(1-\eta_{\nu})\mathsf{L}_{\nu}\rho_t\mathsf{L}_{\nu}^{\dagger}dt + \sum_{\mu}(1-\bar{\eta}_{\mu})\mathsf{V}_{\mu}\rho_t\mathsf{V}_{\mu}^{\dagger}dt}{\mathsf{Tr}\left(\mathsf{M}_{dy_t}\rho_t\mathsf{M}_{dy_t}^{\dagger} + \sum_{\nu}(1-\eta_{\nu})\mathsf{L}_{\nu}\rho_t\mathsf{L}_{\nu}^{\dagger}dt + \sum_{\mu}(1-\bar{\eta}_{\mu})\mathsf{V}_{\mu}\rho_t\mathsf{V}_{\mu}^{\dagger}dt\right)}$$

with $M_{dy_t} = I - \left(iH + \frac{1}{2}\sum_{\nu}L_{\nu}^{\dagger}L_{\nu} + \frac{1}{2}\sum_{\mu}V_{\mu}^{\dagger}V_{\mu}\right)dt + \sum_{\nu}\sqrt{\eta_{\nu}}dy_{\nu t}L_{\nu}$ and where $dy_{\nu,t} = \sqrt{\eta_{\nu}} \operatorname{Tr}\left(\left(L_{\nu} + L_{\nu}^{\dagger}\right)\rho_{t}\right)dt + dW_{\nu,t}.$ If for some μ , $dN_{\nu,t} = 1$ (probability $\left(\bar{\theta}_{\nu} + \sum_{\nu}\sqrt{\eta_{\nu}} - rr\left(V_{\nu,\ell}q_{\nu}V_{\nu}^{\dagger}\right)\right)dt$) we have

If, for some μ , $dN_{\mu,t} = 1$ (probability $\left(\bar{\theta}_{\mu} + \sum_{\mu'} \bar{\eta}_{\mu,\mu'} \operatorname{Tr} \left(\mathsf{V}_{\mu'} \rho_t \mathsf{V}_{\mu'}^{\dagger} \right) \right) dt$) we have

$$\rho_{t+dt} = \frac{\mathsf{M}_{dy_t}\,\tilde{\rho}_t\,\mathsf{M}_{dy_t}^{\dagger} + \sum_{\nu}(1-\eta_{\nu})\mathsf{L}_{\nu}\,\tilde{\rho}_t\mathsf{L}_{\nu}^{\dagger}dt + \sum_{\mu'}(1-\bar{\eta}_{\mu'})\mathsf{V}_{\mu'}\,\tilde{\rho}_t\mathsf{V}_{\mu'}^{\dagger}dt}{\mathsf{Tr}\left(\mathsf{M}_{dy_t}\,\tilde{\rho}_t\,\mathsf{M}_{dy_t}^{\dagger} + \sum_{\nu}(1-\eta_{\nu})\mathsf{L}_{\nu}\,\tilde{\rho}_t\mathsf{L}_{\nu}^{\dagger}dt + \sum_{\mu'}(1-\bar{\eta}_{\mu'})\mathsf{V}_{\mu'}\,\tilde{\rho}_t\mathsf{V}_{\mu'}^{\dagger}dt\right)}$$

with
$$\tilde{\rho}_t = \frac{\bar{\theta}_{\mu} \rho_t + \sum_{\mu'} \bar{\eta}_{\mu,\mu'} \mathbf{v}_{\mu'} \rho_t \mathbf{v}_{\mu'}^{\dagger}}{\bar{\theta}_{\mu} + \sum_{\mu'} \bar{\eta}_{\mu,\mu'} \operatorname{Tr} \left(\mathbf{v}_{\mu'} \rho_t \mathbf{v}_{\mu'}^{\dagger} \right)}.$$

⁹ H. Amini, C. Pellegrini, and PR. Stability of continuous-time quantum filters with measurement imperfections. *Russian Journal of Mathematical Physics*, 21(3):297–315–, 2014.

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Intoduction

Discrete-time SME

Photons measured by dispersive qubits

Photons measured by resonant qubits

Measurement errors

Stochastic Master Equation (SME) in discrete-time

${\tt Continuous-time} \ {\tt Wiener} \ {\tt SME}$

Qubits measured by dispersive photons (discrete-time) Continuous-time diffusive limit

Diffusive SME

Kraus maps and numerical schemes for diffusive SME

Continuous-time Poisson SME

Qubits measured by photons (resonant interaction)

Towards jump SME

Jump SME in continuous-time

Continous-time Wiener/Poisson SME

Conclusion



Four features¹⁰:

- 1. Bayes law: $\mathbb{P}(\mu'/\mu) = \mathbb{P}(\mu/\mu')\mathbb{P}(\mu') / (\sum_{\nu'} \mathbb{P}(\mu/\nu')\mathbb{P}(\nu'))$,
- 2. Schrödinger equations defining unitary transformations.
- 3. Randomness, irreversibility and dissipation induced by the measurement of observables with degenerate spectra.
- 4. Entanglement and tensor product for composite systems.

⇒ Discrete-time models with parameter p Take a set of operators M^{p}_{μ} satisfying $\sum_{\mu} (M^{p}_{\mu})^{\dagger} M^{p}_{\mu} = I$ and a left stochastic matrices $(\eta^{p}_{y_{t},\mu})$. Consider the following Markov process of state ρ (density op.)and measured output y:

 $\rho_{t+1} = \frac{\mathcal{K}_{y_{t}}^{p}(\rho_{t})}{\operatorname{Tr}(\mathcal{K}_{y_{t}}^{p}(\rho_{t}))}, \text{ with proba. } \mathbb{P}_{y_{t}}(\rho_{t}) = \operatorname{Tr}\left(\mathcal{K}_{y_{t}}^{p}(\rho_{t})\right)$

with $\mathcal{K}_{y}^{p}(\rho) = \sum_{\mu=1}^{m} \eta_{y,\mu}^{p} M_{\mu}^{p} \rho(M_{\mu}^{p})^{\dagger}$. It is associated to the Kraus map (ensemble average, quantum channel)

$$\mathbb{E}\left(\rho_{t+1}|\rho_t \mid =\right) \mathcal{K}^{\mathsf{p}}(\rho_t) = \sum_{\mathsf{y}} \mathcal{K}^{\mathsf{p}}_{\mathsf{y}}(\rho_t) = \sum_{\mu} \mathsf{M}^{\mathsf{p}}_{\mu} \rho_t (\mathsf{M}^{\mathsf{p}}_{\mu})^{\dagger}.$$

¹⁰See the book of S. Haroche and J.M. Raimond.



Intoduction

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Conclusion

Filtering and parameter estimation

Feedback schemes

Computation of the likelihood function via the adjoint state (1)

► Denote by $\mathbb{P}_n(\rho, \mathbf{p})$ the probability of getting measurement trajectory n, $(\mathbf{y}_t^{(n)})_{t=0,...,T}$, knowing the initial state $\rho_0^{(n)} = \rho$ and parameter \mathbf{p} .

Since
$$\rho_{t+1}^{(n)} = \frac{\mathcal{K}_{\mathbf{y}_{t}^{(n)}}^{\mathbf{p}_{t}(n)}\left(\rho_{t}^{(n)}\right)}{\operatorname{Tr}\left(\mathcal{K}_{\mathbf{y}_{t}^{(n)}}^{\mathbf{p}_{t}(n)}\left(\rho_{t}^{(n)}\right)\right)}$$
 with $\operatorname{Tr}\left(\mathcal{K}_{\mathbf{y}_{t}^{(n)}}^{\mathbf{p}_{t}(n)}\left(\rho_{t}^{(n)}\right)\right)$ the probability

of having detected $\mathbf{y}_t^{(n)}$ knowing $\rho_t^{(n)}$ and \mathbf{p} , a direct use of Bayes law yields

$$\mathbb{P}_{n}(\boldsymbol{\rho}, \mathbf{p}) = \prod_{t=0}^{T} \operatorname{Tr}\left(\mathcal{K}_{\mathbf{y}_{t}^{(n)}}^{\mathbf{p}}\left(\boldsymbol{\rho}_{t}^{(n)}\right)\right) = \operatorname{Tr}\left(\mathcal{K}_{\mathbf{y}_{T}^{(n)}}^{\mathbf{p}} \circ \ldots \circ \mathcal{K}_{\mathbf{y}_{0}^{(n)}}^{\mathbf{p}}\left(\boldsymbol{\rho}\right)\right).$$

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Computation of the likelihood function via the adjoint state (2)

▶ With adjoint map \mathcal{K}_{y}^{p*} ($\forall A, B, Tr(\mathcal{K}_{y}^{p}(A) B) \equiv Tr(A \mathcal{K}_{y}^{p*}(B))$):

$$\mathbb{P}_{n}(\rho, p) = \operatorname{Tr}\left(\mathcal{K}_{y_{\mathsf{T}}^{(n)}}^{\mathsf{p}} \circ \ldots \circ \mathcal{K}_{y_{\mathsf{0}}^{(n)}}^{\mathsf{p}}(\rho) \quad \mathsf{I}\right) = \operatorname{Tr}\left(\rho \quad \mathcal{K}_{y_{\mathsf{0}}^{(n)}}^{\mathsf{p}*} \circ \ldots \circ \mathcal{K}_{y_{\mathsf{T}}^{(n)}}^{\mathsf{p}*}(\mathsf{I})\right).$$

► Normalized adjoint quantum filter¹¹ $E_t^{(n)} = \frac{\kappa_{y_t^{(n)}}^{p_t}(E_{t+1}^{(n)})}{\operatorname{Tr}\left(\kappa_{y(n)}^{p_t}(E_{t+1}^{(n)})\right)}$ with

$$\begin{split} E_{\mathcal{T}+1}^{(n)} &= \mathsf{I}/\operatorname{Tr}(\mathsf{I}), \text{ we get} \\ \mathbb{P}_n(\rho, \mathsf{p}) &= \prod_{t=\mathcal{T}}^0 \operatorname{Tr}\left(\mathcal{K}_{\mathsf{y}_t^{(n)}}^{\mathsf{p}*}\left(\mathcal{E}_{t+1}^{(n)}\right)\right) \operatorname{Tr}\left(\rho \mathcal{E}_0^{(n)}\right) \triangleq g_n(\mathsf{Y}, \mathsf{p}) \operatorname{Tr}\left(\rho \mathcal{E}_0^{(n)}\right). \end{split}$$

A simple expression of the gradients:

$$\nabla \rho \log \mathbb{P}_{n} = \frac{E_{0}^{(n)}}{\operatorname{Tr}\left(\rho E_{0}^{(n)}\right)}, \quad \nabla_{p} \log \mathbb{P}_{n} \cdot \delta p = \sum_{t=0}^{T} \frac{\operatorname{Tr}\left(E_{t+1}^{(n)}\left(\nabla_{p} \mathcal{K}_{y_{t}^{(n)}}^{p}\left(\rho_{t}^{(n)}\right) \cdot \delta p\right)\right)}{\operatorname{Tr}\left(E_{t+1}^{(n)} \mathcal{K}_{y_{t}^{(n)}}^{p}\left(\rho_{t}^{(n)}\right)\right)},$$

¹¹M. Tsang. Time-symmetric quantum theory of smoothing. PRL 2009. S. Gammelmark, B. Julsgaard, and K. Mølmer. Past quantum states of a monitored system. PRL 2013. PSI 🕷

MaxLike tomography based on N trajectories data $\mathsf{Y} = \left\{\mathsf{y}_{\mathsf{t=0},...,\mathsf{T}}^{(\mathsf{n=1},...,\mathsf{N})}
ight\}$

From $\mathbb{P}_{n}(\rho, p) = g_{n}(\mathbf{Y}, p) \operatorname{Tr}\left(\rho E_{0}^{(n)}\right)$ we have $\mathbb{P}(\rho, p) \triangleq \prod_{n=1}^{N} \mathbb{P}_{n}(\rho, p) = \left(\prod_{n=1}^{N} g_{n}(\mathbf{Y}, p)\right) \left(\prod_{n=1}^{N} \operatorname{Tr}\left(\rho E_{0}^{(n)}\right)\right).$

• MaxLike state tomography: p is known and ρ_{ML} maximizes

$$\rho \mapsto \sum_{n=1}^{N} \log \left(\operatorname{Tr} \left(\rho E_{0}^{(n)} \right) \right)$$

a concave function on the convex set of density operators ρ : a well structured convex optimization problem.

• MaxLike process tomography: ρ is known and p_{ML} maximizes $\mathbf{p} \mapsto f(\mathbf{p}) = \log \mathbb{P}(\rho, \mathbf{p})$ those gradient is given by $\nabla_{\mathbf{p}} f(\mathbf{p}) \cdot \delta \mathbf{p} = \sum_{n=1}^{N} \sum_{t=0}^{T} \frac{\operatorname{Tr}\left(E_{t+1}^{(n)}\left(\nabla_{\mathbf{p}} \mathcal{K}_{\mathbf{y}_{t}^{(n)}}^{\mathbf{p}}(\rho_{t}^{(n)}) \cdot \delta \mathbf{p}\right)\right)}{\operatorname{Tr}\left(E_{t+1}^{(n)} \mathcal{K}_{\mathbf{y}_{t}^{(n)}}^{\mathbf{p}}(\rho_{t}^{(n)})\right)},$

The Hessian $\nabla_{p}^{2}f$ can be computed similarly (Fisher information).

MINES PARIS

Stability issues



► Adjoint map (unital map) A_{k+1} = K^{*}(A_k) contracts spectrum¹³:

$$\lambda_{\min}(A_k) \leq \lambda_{\min}(A_{k+1}) \leq \lambda_{\max}(A_{k+1}) \leq \lambda_{\max}(A_k).$$

• Quantum filter
$$\hat{\rho}_{k+1} = \frac{\mathcal{K}_{Y_k}(\hat{\rho}_k)}{\operatorname{Tr}(\mathcal{K}_{Y_k}(\hat{\rho}_k))}$$
 where y_k is governed by
 $\rho_{k+1} = \frac{\mathcal{K}_{Y_k}(\rho_k)}{\operatorname{Tr}(\mathcal{K}_{Y_k}(\rho_k))}$ with $\hat{\rho}_0 \neq \rho_0$: fidelity $\operatorname{Tr}^2\left(\sqrt{\sqrt{\hat{\rho}_k}\rho_k\sqrt{\hat{\rho}_k}}\right)$ is always a sub-martingale¹⁴

Convergence issues around filtering and parameter estimation along quantum trajectories: seminal works of Belavkin in continuous-time, Van-Handel thesis at Caltech 2007. See also recent works of Nina Amini, Maël Bompais, Tristan Benoit and Clément Pellegrini.

¹²D. Petz. Monotone metrics on matrix spaces. *Linear Algebra and its Applications*, 244:81–96, 1996.

¹³R. Sepulchre, A. Sarlette, and PR.. Consensus in non-commutative spaces.
 In Decision and Control (CDC), 2010 49th IEEE Conference on, pages 6596–6601, 2010.

¹⁴PR. Fidelity is a sub-martingale for discrete-time quantum filters. *IEEE Transactions on Automatic Control*, 56(11):2743–2747, 2011.



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Filtering and parameter estimation

Feedback schemes

Measurement-based feedback





- ▶ P-controller (Markovian feedback¹⁵) for $u_t dt = k dy_t$, the ensemble average closed-loop dynamics of ρ remains governed by a linear Lindblad master equation.
- PID controller: no Lindblad master equation in closed-loop for dynamics output feedback
- Nonlinear hidden-state stochastic systems: Lyapunov state-feedback¹⁶; many open issues on convergence rates, delays, robustness, ...

Short sampling times limit feedback complexity

¹⁵ H. Wiseman, G. Milburn (2009). Quantum Measurement and Control. Cambridge University Press.
 ¹⁶ See e.g.: C. Ahn et. al (2002): Continuous quantum error correction via quantum feedback control. Phys. Rev. A 65:

M. Mirrahimi, R. Handel (2007): Stabilizing feedback controls for quantum systems. SIAM Journal on Control and Optimization, 46(2), 445-467;

G. Cardona, A. Sarlette, PR (2019): Continuous-time quantum error correction with noise-assisted quantum feedback. IFAC Mechatronics & Nolcos Conf.

Coherent (autonomous) feedback (dissipation engineering)



CLASSICAL WORLD



Optical pumping (Kastler 1950), coherent population trapping (Arimondo 1996)

Dissipation engineering, autonomous feedback: (Zoller, Cirac, Wolf, Verstraete, Devoret, Schoelkopf, Siddiqi, Martinis, Mølmer, Raimond, Brune,..., Lloyd, Viola, Ticozzi, Leghtas, Mirrahimi, Sarlette, PR, ...)

(S,L,H) theory and linear quantum systems: quantum feedback networks based on stochastic Schrödinger equation, Heisenberg picture (Gardiner, Yurke, Mabuchi, Genoni, Serafini, Milburn, Wiseman, Doherty, ..., Gough, James, Petersen, Nurdin, Yamamoto, Zhang, Dong, ...)

Stability analysis: Kraus maps and Lindblad propagators are always contractions (non commutative diffusion and consensus).

¹⁷ J.C. Maxwell (1868): On governors. Proc. of the Royal Society, No.100.

Coherent feedback involves tensor products and many time-scales

The closed-loop Lindblad master equation on $\mathcal{H} = \mathcal{H}_s \otimes \mathcal{H}_c$:

$$\frac{d}{dt}\rho = -i\Big[\mathsf{H}_{s}\otimes\mathsf{I}_{c}+\mathsf{I}_{s}\otimes\mathsf{H}_{c}+\mathsf{H}_{sc}\;,\;\rho\Big] + \sum_{\nu}\mathbb{D}_{\mathsf{L}_{s,\nu}\otimes\mathsf{I}_{c}}(\rho) + \sum_{\nu'}\mathbb{D}_{\mathsf{I}_{s}\otimes\mathsf{L}_{c,\nu'}}(\rho)$$

with $\mathbb{D}_{\mathsf{L}}(\rho) = \mathsf{L}\rho\mathsf{L}^{\dagger} - \frac{1}{2}\left(\mathsf{L}^{\dagger}\mathsf{L}\rho + \rho\mathsf{L}^{\dagger}\mathsf{L}\right)$ and operators made of tensor products.

• Consider a convex subset $\overline{\mathcal{D}}_s$ of steady-states for original system S: each density operator $\overline{\rho}_s$ on \mathcal{H}_s belonging to $\overline{\mathcal{D}}_s$ satisfy $i[\mathsf{H}_s, \overline{\rho}_s] = \sum_{\nu} \mathbb{D}_{\mathsf{L}_{s,\nu}}(\overline{\rho}_s)$.

• Designing a **realistic** quantum controller $C(H_c, L_{c,\nu'})$ and coupling Hamiltonian H_{sc} stabilizing $\overline{\mathcal{D}}_s$ is non trivial. **Realistic** means in particular relying on physical time-scales and constraints:

- ► Fastest time-scales attached to H_s and H_c (Bohr frequencies) and averaging approximations: ||H_s||, ||H_c|| ≫ ||H_{sc}||,
- ► High-quality oscillations: $||H_s|| \gg ||L_{s,\nu}^{\dagger}L_{s,\nu}||$ and $||H_c|| \gg ||L_{c,\nu'}^{\dagger}L_{c,\nu'}||$.
- Decoherence rates of S much slower than those of C: ||L[†]_{s,\nu}L_{s,ν}|| ≪ ||L[†]_{c,ν'}L_{c,ν'}||: model reduction by quasi-static approximations (adiabatic elimination, singular perturbations).

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Quantum feedback engineering for robust quantum information processing



To protect quantum information stored in system S (alternative to usual QEC):

- fast stabilization and protection mainly achieved by a quantum controller (coherent feedback stabilizing decoherence-free sub-spaces);
- slow decoherence and perturbations mainly tackled by a classical controller (measurement-based feedback "finishing the job")

Underlying mathematical methods for high-precision dynamical modeling and control based on stochastic master equations (SME):

- High-order averaging methods and geometric singular perturbations for coherent feedback.
- Stochastic control Lyapunov methods for exponential stabilization via measurement-based feedback.

Quantic research group ENS/Inria/Mines/CNRS, March 2022



